

Adam Smith Business School

WORKING PAPER SERIES



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Gary Koop and Dimitris Korobilis

Paper no. 2020-11 May 2020

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Gary Koop
University of Strathclyde

Dimitris Korobilis * University of Glasqow

Abstract

This paper proposes a variational Bayes algorithm for computationally efficient posterior and predictive inference in time-varying parameter (TVP) models. Within this context we specify a new dynamic variable/model selection strategy for TVP dynamic regression models in the presence of a large number of predictors. This strategy allows for assessing in individual time periods which predictors are relevant (or not) for forecasting the dependent variable. The new algorithm is evaluated numerically using synthetic data and its computational advantages are established. Using macroeconomic data for the US we find that regression models that combine time-varying parameters with the information in many predictors have the potential to improve forecasts of price inflation over a number of alternative forecasting models.

Keywords: dynamic linear model; approximate posterior inference; dynamic variable selection; forecasting

JEL Classification: C11, C13, C52, C53, C61

^{*}Corresponding Author: Adam Smith Business School, University of Glasgow, G12 8QQ Glasgow, UK, email: Dimitris.Korobilis@glasgow.ac.uk

1 Introduction

Regression models that incorporate stochastic variation in parameters have been used by economists at least since the work Cooley and Prescott (1976). Thirty years later, Granger (2008) argued that time-varying parameter models might become the norm in econometric inference since, as he illustrated via White's theorem, time variation is able to approximate generic forms of nonlinearity in parameters. Indeed, initiated by the unprecedented shocks observed during and after the Global Recession of 2007-9, a large recent literature has established the importance of modeling time variation in the intercept, slopes and variance of regressions for forecasting economic time series; see Stock and Watson (2007) for a representative example of a model using only a stochastic intercept and volatilities. At the same time, the stylized fact that economic predictors are short-lived – that is, relevant for the dependent variable only in short periods¹ – has emerged in various forecasting problems such as inflation (Koop and Korobilis, 2012), stock returns (Dangl and Halling, 2012) and exchange rates (Byrne et al., 2018). Following these observations, there is no shortage of recent econometric work on methods for penalized estimation of time-varying parameter models via classical or Bayesian shrinkage, as well as variable selection methods; see for example Belmonte et al. (2014), Bitto and Frühwirth-Schnatter (2019), Kalli and Griffin (2014), Callot and Kristensen (2014), Korobilis (2019), Kowal et al. (2019), Nakajima and West (2013), Ročková and McAlinn (2017), Uribe and Lopes (2017) and Yousuf and Ng (2019).

In this paper we add to this literature by proposing a new dynamic variable selection prior and a novel, for the field of economics, Bayesian estimation methodology. In particular, we propose to use variational Bayes (VB) inference to estimate time-varying parameter regressions using state-space methods. Variational inference has long been used in data science problems such as large-scale document analysis, computational neuroscience, and computer vision (Blei et al., 2017). Nevertheless, it is only relatively recently that posterior consistency and other theoretical properties of these methods have been explored by mainstream statisticians (Wang and Blei, 2019). Variational inference is a unified estimation methodology which shares similarities with the Gibbs sampler that many economists traditionally use to estimate time-varying parameter models (see for example Stock and Watson, 2007). Like the Gibbs sampler, parameter updates are derived for one parameter at a time conditional on all other parameters using an iterative scheme. Unlike the Gibbs sampler, there is no repeated sampling involved and the output of VB is typically the first

¹An alternative terminology for such periods, which is due to Farmer et al. (2018), is "pockets of predictability".

two moments of the posterior distribution of parameters. Our first task is to introduce this estimation scheme in the context of TVP regressions, and contrast it to existing estimation algorithms used in economics for capturing structural change.

Our second contribution lies on the development of a dynamic variable selection prior that is a conceptually straightforward extension of the static variable selection prior of George and McCulloch (1993). The dynamic extension of this prior allows to tackle the non-trivial econometric problem of allowing some predictor variables to enter the TVP regression, model only in some periods of the full estimation sample. With p predictors and T time periods, dynamic variable selection involves choosing the "best" among 2^p models at each point in time t, for t = 1, ..., T. Such procedure is in line with strong, recent empirical evidence that different factors might be driving predictability of economic variables over time; see Rossi (2013) for a thorough review of this idea. By specifying our new prior within a variational Bayes framework, we are able to derive an algorithm that is numerically stable and can be extended to much larger p and T than was possible before.²

We show, via a Monte Carlo exercise and an empirical application, that our proposed algorithm works well in high-dimensional, sparse, time-varying parameter settings. Using artificial data we establish that the new algorithm is precise in estimation and in dynamic variable selection, even in settings with more predictors than time-series observations. In a forecasting exercise of various measures of price inflation, we illustrate that our methodology applied to a time-varying parameter regression with 400+ predictors is able to beat a wide range of linear and nonlinear forecasting regressions. The empirical results provide strong evidence that the new algorithm can achieve estimation accuracy comparable to Markov chain Monte Carlo algorithms, while being much faster to run. The additional feature of dynamic variable selection successfully prevents overparametrization, since our high-dimensional TVP specification is able to beat both parsimonious time series models with no predictors as well as factor models and penalized likelihood estimators.

The remainder of the paper proceeds as follows. Section 2 introduces the basic principles of VB inference for approximating intractable posteriors, and applies these principles to the problem of estimating a simplified time-varying parameter regression model. Section 3 introduces the novel modelling assumptions, namely dynamic variable selection and stochastic volatility, and derives an estimation algorithm within the VB framework. Section 4 assesses the new algorithm on simulated data. In Section 5 we apply the new methodology to the problem of forecasting US inflation using time-varying parameter regressions with many predictors.

²In particular, many of the algorithms cited above, such as Koop and Korobilis (2012), Kalli and Griffin (2014), or Nakajima and West (2013), are unable to scale up to regressions with hundreds of predictors.

2 Variational Bayes inference in state-space models

as variational Bayes (VB) is not an established estimation methodology in econometrics, we first provide a generic discussion of VB methods in approximating intractable posterior distributions. We then apply the generic concepts and formulas to the specific problem of estimating a simplified time-varying parameter regression model with known measurement error variance.³ Detailed reviews of variational Bayes can be found in Blei et al. (2017) and Ormerod and Wand (2010), among several others. Variational Bayes estimation of state-space models is described in detail in the monograph of Šmídl and Quinn (2006), as well as research papers such as Beal and Ghahramani (2003), Tran et al. (2017), and Wang et al. (2016).

2.1 Basics of variational Bayes

Consider data y, latent variables s and (latent) parameters θ . Our interest lies in time-varying parameter models that admit a state-space form. Hence, s represents unobserved state variables, such as time-varying regression coefficients and time-varying measurement error variances, and θ represents all other parameters, such as the error covariances in the state equation. The joint posterior of interest is $p(s,\theta|y)$ with associated marginal likelihood p(y) and joint density of data and parameters $p(y,s,\theta)$. When the joint posterior is complex and computationally intractable, we can define an approximating density $q(s,\theta|y)$ that belongs to a family \mathcal{F} of simpler distributions defined over the parameter space spanned by s,θ . The main idea behind variational Bayes inference is to make this approximating posterior distribution $q(s,\theta|y)$ as close as possible to $p(s,\theta|y)$, where "distance" is measured with the Kullback-Leibler divergence⁴

$$KL(q||p) = \int q(s,\theta|y) \log \left\{ \frac{q(s,\theta|y)}{p(s,\theta|y)} \right\} ds d\theta.$$
 (1)

That is, the aim is to find the optimal $q^*(s, \theta|y)$ that solves

$$q^{\star}(s,\theta|y) = \underset{q(s,\theta|y) \in \mathcal{F}}{\arg\min} KL(q||p).$$
(2)

Insight for why KL(q||p) is a desirable distance metric arises from a simple re-arrangement involving the log of the marginal likelihood (Ormerod and Wand, 2010, page 142) where it

³Readers already familiar with these concepts can skim through this section, and focus on our novel methodology that is described in the following section

⁴For notational simplicity we henceforth abbreviate multiple integrals using a single integration symbol.

can be shown that

$$\log p(y) = \log p(y) \int p(s, \theta|y) \, ds d\theta = \int p(s, \theta|y) \log p(y) \, ds d\theta \tag{3}$$

$$= \int q(s,\theta|y) \log \left\{ \frac{p(y,s,\theta)/q(s,\theta|y)}{p(s,\theta|y)/q(s,\theta|y)} \right\} ds d\theta \tag{4}$$

$$= \int q(s,\theta|y) \log \left\{ \frac{p(y,s,\theta)}{q(s,\theta|y)} \right\} ds d\theta + KL(q||p).$$
 (5)

Because KL(q||p) is non-negative (it is exactly zero when $q(s,\theta|y) = p(s,\theta|y)$), the quantity

$$\mathcal{E}\left(q(s,\theta|y)\right) = \exp\left[\int q\left(s,\theta|y\right)\log\left\{\frac{p\left(y,s,\theta\right)}{q\left(s,\theta|y\right)}\right\}dsd\theta\right] \equiv \exp\left[\mathbb{E}_{q\left(s,\theta|y\right)}\left(\log\left(p\left(y,s,\theta\right)\right) - \log\left(q\left(s,\theta|y\right)\right)\right)\right],\tag{6}$$

becomes a lower bound for the marginal likelihood p(y).⁵ The function $\mathcal{G}(q(s,\theta|y))$ is known as the Evidence Lower Bound (ELBO). Therefore, instead of minimizing the objective function KL(q||p) (which cannot be evaluated) we can find an approximating density $q^*(s,\theta|y)$ that maximizes the marginal data density p(y) by maximizing the ELBO. We emphasize that \mathcal{G} is a functional on the distribution $q(s,\theta|y)$. As a result, the ELBO can be maximized iteratively using calculus of variations.

If we assume for simplicity the so-called (in Physics) mean field factorization of the form $q(s, \theta|y) = q(\theta|y) q(s|y)$, it can be shown⁶ that the optimal choices for q(s|y) and $q(\theta|y)$ are

$$q(s|y) \propto \exp\left[\int q(\theta|y)\log p(s|y,\theta)\,\mathrm{d}\theta\right] \equiv \exp\left[\mathbb{E}_{q(\theta|y)}\left(\log p(s|y,\theta)\right)\right],$$
 (7)

$$q(\theta|y) \propto \exp\left[\int q(s|y)\log p(\theta|y,s)\,\mathrm{d}s\right] \equiv \exp\left[\mathbb{E}_{q(s|y)}\left(\log p(\theta|y,s)\right)\right].$$
 (8)

The first expression denotes the expectation over $q(\theta|y)$ of the conditional posterior for s, and the second expression denotes the expectation over q(s|y) of the conditional posterior for θ . Because $q(\theta|y)$ is a function of q(s|y), and vice-versa, the above quantities can be approximated iteratively instead of relying on more computationally expensive numerical optimization techniques. Given an initial guess regarding the values of (θ, s) , VB algorithms iterate over these two quantities until $\mathcal{G}(q(s, \theta|y))$ has reached a maximum. Due to similarities with the Expectation-Maximization (EM) algorithm of Dempster et al. (1977), this iterative procedure in its general form is sometimes referred to as the *Variational Bayesian EM (VB-EM)* algorithm; see Beal and Ghahramani (2003). It is also worth noting

⁵In the following we denote as $\mathbb{E}_{q(\bullet)}$ the expectation w.r.t to a function $q(\bullet)$.

⁶A formal and thorough derivation of these ideas is given in the excellent monograph of Šmídl and Quinn (2006); see Theorem 3.1 and subsequent results.

the relationship with Gibbs sampling. Like Gibbs sampling, equations (7) and (8) involve the full conditional posterior distributions. But unlike Gibbs sampling, the VB-EM algorithm does not repeatedly simulate from them and is computationally much faster.

2.2 VB estimation of a simple TVP regression model

Before collecting all building blocks of our proposed methodology, we outline a VB algorithm for the univariate TVP regression with known measurement error variance $\underline{\sigma}^2$. This simplified model is of the form

$$y_t = \mathbf{x}_t \boldsymbol{\beta}_t + \varepsilon_t \tag{9}$$

$$\boldsymbol{\beta}_t = \boldsymbol{\beta}_{t-1} + \boldsymbol{\eta}_t \tag{10}$$

where y_t is the time t scalar value of the dependent variable, t = 1, ..., T, \mathbf{x}_t is a $1 \times p$ vector of exogenous predictors and lagged dependent variables, $\varepsilon_t \sim N\left(0,\underline{\sigma}^2\right)$, $\boldsymbol{\eta}_t \sim N\left(0,\boldsymbol{W}_t\right)$ with $\boldsymbol{W}_t = diag\left(w_{1,t},...,w_{p,t}\right)$ a $p \times p$ diagonal matrix⁷ and $\boldsymbol{w}_t = [w_{1,t},...,w_{p,t}]'$ a $p \times 1$ vector. In likelihood-based analysis of state-space models it simplifies inference if it is assumed that ε_t and $\boldsymbol{\eta}_t$ are independent of one another and we do adopt this assumption here. Finally, we use a notational convention where j,t subscripts denote the j^{th} element of a time varying state variable, or parameter, observed only at time t, while 1:t subscripts denote all the observations of a state variable from period 1 up to period t.

The model in equations (9) and (10) has unknown parameters ($\boldsymbol{\beta}_{1:T}, \boldsymbol{w}_{1:T}$). Following the analysis of the previous subsection we first consider the independent prior on the initial conditions $\boldsymbol{\beta}_0, \boldsymbol{w}_0$ of the form

$$p(\boldsymbol{\beta}_0, \boldsymbol{w}_0) = p(\boldsymbol{\beta}_0) \prod_{j=1}^p p(w_{j,0}) = N(\boldsymbol{m}_0, \boldsymbol{P}_0) \times \prod_{j=1}^p \left[Gamma(c_{j,0}, d_{j,0}) \right]^{-1},$$
(11)

where $w_{j,0}$ is the j^{th} element of w_0 , and Gamma(a, b) denotes the Gamma distribution with shape parameter a and rate parameter b, that is, the definition of the Gamma distribution that has mean a/b and variance a/b^2 . The time t prior, conditional on observing information

⁷By restricting W_t not to be a full covariance matrix, coefficients β_{it} and β_{jt} are uncorrelated a-posteriori for $i \neq j$, which might not seem like an empirically relevant assumption. However, allowing for cross-correlation in the state vector $\boldsymbol{\beta}_t$ can result in counterproductive increases in estimation uncertainty, with this problem being significantly more pronounced in higher dimensions. A diagonal \boldsymbol{W}_t allows for a more parsimonious econometric specification, less cumbersome derivations of posterior distributions, and faster and numerically stable computation; see also Belmonte et al. (2014), Bitto and Frühwirth-Schnatter (2019) and Ročková and McAlinn (2017) who adopt a similar assumption.

up to time t-1, is given by the Chapman-Kolmogorov equation

$$p(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t-1}) = \int_{\mathfrak{B}, \mathcal{W}} p(\boldsymbol{\beta}_{t} | \boldsymbol{\beta}_{t-1}) \prod_{j=1}^{p} p(w_{j,t} | w_{j,t-1}) \times p(\boldsymbol{\beta}_{t-1}, \boldsymbol{w}_{t-1} | y_{t-1}) d\boldsymbol{\beta}_{t-1} dw_{1,t-1} ... dw_{p,t-1},$$

$$(12)$$

where \mathcal{B} is the support of β_t and \mathcal{W} the support of all $w_{j,t}$. Finally, once the measurement y_t is observed, we obtain from Bayes theorem the following time t posterior distribution

$$p(\boldsymbol{\beta}_t, \boldsymbol{w}_t | \boldsymbol{y}_{1:t}) \propto p(y_t | \boldsymbol{\beta}_t, \boldsymbol{w}_t) p(\boldsymbol{\beta}_t, \boldsymbol{w}_t | \boldsymbol{y}_{1:t-1}).$$
 (13)

This Bayesian joint posterior distribution is rarely analytically tractable, even if conjugate prior densities have been specified. However, posterior conditionals can be tractable, and this is why in macroeconomics TVP models are predominantly estimated using the Gibbs sampler; see Stock and Watson (2007) for an example. Nevertheless, sampling repeatedly using (Markov chain) Monte Carlo methods is computationally prohibitive in high-dimensional settings or in settings with more flexible likelihood and prior distributions. For that reason we define a tractable variational density as an approximation to the exact intractable time t posterior, that is, we define $p(\beta_t, \mathbf{w}_t | \mathbf{y}_{1:t}) \approx q(\beta_t, \mathbf{w}_t | \mathbf{y}_{1:t})$. Among all possible functions $q(\beta_t, \mathbf{w}_t | \mathbf{y}_{1:t})$ we want to obtain the one that has hyperparameters that minimize the relative entropy with the true posterior. Following the discussion earlier in this section, this problem is equivalent to maximizing the evidence lower bound (ELBO) of the log-marginal likelihood, that is, it is the solution to

$$q^{\star}\left(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t}\right) = \underset{q(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t})}{\arg\max} \int q\left(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t}\right) \log\left(\frac{q\left(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t}\right)}{p\left(\boldsymbol{\beta}_{t}, \boldsymbol{w}_{t} | \boldsymbol{y}_{1:t}\right)}\right). \tag{14}$$

This maximization problem is simplified once we assume the mean field factorization of the form $q(\boldsymbol{\beta}_t, \boldsymbol{w}_t | \boldsymbol{y}_{1:t}) = q(\boldsymbol{\beta}_t | \boldsymbol{y}_{1:t}) \prod q(\boldsymbol{w}_{j,t} | \boldsymbol{y}_{1:t})$ so we can optimize $\boldsymbol{\beta}_t$ and \boldsymbol{w}_t sequentially. As a result, using variational calculus (Šmídl and Quinn, 2006) we can show that the ELBO is maximized by iterating through the following recursions

$$q\left(\boldsymbol{\beta}_{t}|\boldsymbol{y}_{1:t}\right) \propto \exp\left(\int \log p\left(y_{t},\boldsymbol{\beta}_{t},\boldsymbol{w}_{t}|\boldsymbol{y}_{1:t-1}\right)\prod_{j}q\left(w_{j,t}|\boldsymbol{y}_{1:t}\right)d\boldsymbol{w}_{t}\right),$$
 (15)

$$q(w_{j,t}|\boldsymbol{y}_{1:t}) \propto \exp\left(\int \log p\left(y_t,\boldsymbol{\beta}_t,\boldsymbol{w}_t|\boldsymbol{y}_{1:t-1}\right)q\left(\boldsymbol{\beta}_t|\boldsymbol{y}_{1:t}\right)d\boldsymbol{\beta}_t\right), j=1,...,p.$$
 (16)

Both formulas above become equalities after the addition of a normalizing constant. The first expression is an expectation with respect to the probability density $\prod_{j} q(w_{j,t}|\boldsymbol{y}_{1:t-1})$,

that is, we can write equation (15) using the following form

$$q\left(\boldsymbol{\beta}_{t}|\boldsymbol{y}_{1:t}\right) \propto \exp\left(\mathbb{E}_{q\left(\boldsymbol{w}_{t}|\boldsymbol{y}_{1:t}\right)}\left(\log p\left(y_{t},\boldsymbol{\beta}_{t},\boldsymbol{w}_{t}|\boldsymbol{y}_{1:t-1}\right)\right)\right)$$
 (17)

$$= \exp\left(\mathbb{E}_{q(\boldsymbol{w}_t|\boldsymbol{y}_{1:t})}\left(\log\left[p\left(y_t|\boldsymbol{\beta}_t,\boldsymbol{w}_t\right)p\left(\boldsymbol{\beta}_t|\boldsymbol{y}_{1:t-1}\right)p\left(\boldsymbol{w}_t|\boldsymbol{y}_{1:t-1}\right)\right]\right)\right)$$
(18)

$$= p(y_t|\boldsymbol{\beta}_t, \boldsymbol{w}_t) \exp\left(\mathbb{E}_{q(\boldsymbol{w}_t|\boldsymbol{y}_{1:t})} \left(\log p\left(\boldsymbol{\beta}_t|\boldsymbol{\beta}_{t-1}\right) + \log q\left(\boldsymbol{\beta}_t|\boldsymbol{y}_{1:t-1}\right)\right)\right) \quad (19)$$

where $q(\boldsymbol{\beta}_t|y_{1:t-1})$ is the time t prior of $\boldsymbol{\beta}_t$ obtained from the time t-1 posterior $q(\boldsymbol{\beta}_{t-1}|\boldsymbol{y}_{1:t-1})$ using the Kalman filter recursions, and the term $p(\boldsymbol{w}_t|\boldsymbol{y}_{1:t-1})$ in (18) disappears because the expectation is w.r.t the variational posterior of w_t . This latter representation of $q(\boldsymbol{\beta}_t|\boldsymbol{y}_{1:t})$ can be trivially updated by a Normal distribution, with moments given by the Kalman filter and smoother; see Šmídl and Quinn (2006, Chapter 7) for detailed derivations. We can use similar arguments in order to show that equation (16) is an expectation that leads to a $q(\boldsymbol{w}_t^{-1}|\boldsymbol{y}_{1:t})$ of the form $G(c_{j,t},d_{j,t})$ (or equivalently to $q(\boldsymbol{w}_t|\boldsymbol{y}_{1:t})$ that is inverse Gamma).

Algorithm 1 Variational Bayes algorithm for TVP regression model with fixed measurement variance

```
1: Choose values of hyperparameters m_0, P_0, c_{j,0}, d_{j,0} for j = 1, ..., p. Set r = 1 and initialize W^{(r-1)}.
```

3: **Step 1:** Approximate, $\forall t = 1, ..., T$, the posterior

$$q^{r}\left(\boldsymbol{\beta}_{t}|\boldsymbol{y}_{1:T}\right) \sim N\left(\boldsymbol{m}_{t}^{r}, \boldsymbol{P}_{t}^{r}\right)$$

conditional on $W^{(r-1)}, \underline{\sigma}^2$, where $m_t^r, P_t^r \, \forall \, t = 1, ..., T$, are obtained using the Kalman filter and the Rauch-Tung-Striebel smoother

4: **Step 2:** Approximate, $\forall t = 1, ..., T$ and j = 1, ..., p, the posterior

$$q^r \left(w_{j,t}^{-1} | \boldsymbol{y}_{1:T} \right) \sim G \left(c_{j,t}^r, d_{j,t}^r \right)$$

 $\begin{aligned} &\text{conditional on } \boldsymbol{\mu}_{t}^{r}, \boldsymbol{P}_{t}^{r}, \text{ where } c_{j,t}^{r} = c_{j,0} + 1/2, d_{j,t}^{r} = d_{j,0} + \boldsymbol{D}_{jj,t}/2 \text{ with } \boldsymbol{D}_{t} = \left(\boldsymbol{P}_{t}^{r} - \boldsymbol{P}_{t-1}^{r}\right) + \left(\boldsymbol{m}_{t}^{(r)} \boldsymbol{m}_{t}^{(r)'} - \boldsymbol{m}_{t-1}^{(r)} \boldsymbol{m}_{t-1}^{(r)'}\right). \end{aligned} \\ &\text{Set } \boldsymbol{W}^{(r)} = diag\left(d_{1,t}^{r}/c_{1,t}^{r}, ..., d_{p,t}^{r}/c_{p,t}^{r}\right). \end{aligned}$

- 5: r = r + 1
- 6: end while
- 7: Upon convergence set $q^{\star}(\boldsymbol{\beta}_{1:T}, \boldsymbol{w}_{1:T}|\boldsymbol{y}_{1:T}) = q^{r}(\boldsymbol{\beta}_{1:T}|\boldsymbol{y}_{1:T}) \times \prod_{j=1}^{p} q^{r}(w_{j,t}|\boldsymbol{y}_{1:T})$ using the parameters $(\boldsymbol{m}_{1:T}^{r}, \boldsymbol{P}_{1:T}^{r}, \boldsymbol{c}_{1:p,1:T}^{r}, \boldsymbol{d}_{1:p,1:T}^{r})$ obtained during the last iteration of the while loop.

Algorithm 1 provides pseudocode for the basic VB estimation problem described in this section, without assuming either a (dynamic) variable selection prior or stochastic volatility in the measurement equation. In the following section we drop these two unrealistic assumptions.

^{2:} while $\|\mathscr{C}\left(q(\boldsymbol{\beta}^{(r)}, \boldsymbol{w}^{(r)}|\boldsymbol{y}\right) - \mathscr{C}\left(q(\boldsymbol{\beta}^{(r-1)}, \boldsymbol{w}^{(r-1)}|\boldsymbol{y}\right)\| \to 0 \text{ do}$

Variational Bayes Inference in High-Dimensional 3 TVP Regressions

We rewrite for convenience the univariate time-varying parameter model

$$y_t = \mathbf{x}_t \boldsymbol{\beta}_t + \varepsilon_t \tag{20}$$

$$\boldsymbol{\beta}_t = \boldsymbol{\beta}_{t-1} + \boldsymbol{\eta}_t \tag{21}$$

where we define now $\varepsilon_t \sim N(0, \sigma_t^2)$ with σ_t^2 a stochastic (time-varying) variance parameter, and we assume that the dimension p of $\beta_t = (\beta_{1,t}, ..., \beta_{p,t})'$ is large and possibly $p \gg T$.

3.1 Dynamic variable selection and averaging

The core ingredient of our modeling approach is a dynamic variable/model selection strategy. We specify a dynamic variable selection (DVS) prior that extends the "static" variable selection prior of George and McCulloch (1993) that was originally developed for the constant parameter regression using MCMC and is of the form

$$\beta_{j,t}|\gamma_{j,t}, \tau_{j,t}^2 \sim (1 - \gamma_{j,t}) N\left(0, \underline{c} \times \tau_{j,t}^2\right) + \gamma_{j,t} N\left(0, \tau_{j,t}^2\right),$$
 (22)

$$\gamma_{i,t}|\pi_t \sim Bernoulli(\pi_{0,t}),$$
 (23)

$$\gamma_{j,t}|\pi_t \sim Bernoulli(\pi_{0,t}),$$

$$\frac{1}{\tau_{j,t}^2} \sim Gamma(g_0, h_0)$$
(23)

$$\pi_{0,t} \sim Beta(1,1), \tag{25}$$

for j = 1, ..., p, where \underline{c} , g_0 and h_0 are fixed prior hyperparameters. Variable selection principles require us to set $\underline{c} \to 0$, such that the first component in the prior for $\beta_{j,t}$ shrinks the posterior towards zero, while the second component has variance $au_{j,t}^2$ which is "large enough" in order to allow for unrestricted estimation. The choice between the two components in the prior for $\beta_{j,t}$ is governed by the random variable $\gamma_{j,t}$ which is distributed Bernoulli and takes values either zero or one. If $\gamma_{j,t} = 1$ the prior for $\beta_{j,t}$ has a Normal prior with zero mean and variance $\tau_{i,t}^2$, while if $\gamma_{j,t} = 0$ the prior variance becomes $\underline{c}\tau_{i,t}^2$.

Early papers such as George and McCulloch (1993) give very broad guidelines on choosing values for \underline{c} and $\tau_{i,t}^2$ such that the first component in equation (22) has small enough variance (to force shrinkage) and the second component has large enough variance (to allow unrestricted estimation). More recently, Narisetty and He (2014) show that selecting and fixing the prior variances of such mixture priors could, as T and p grow, lead to model selection inconsistency. The authors suggest to specify these parameters to be certain deterministic functions of the data dimensions T and p. In our case, we do fix $\underline{c} = 10^{-4}$ such that the first component has always smaller variance, but we assume $(\tau_{j,t}^2)^{-1}$ is a random variable that has a Gamma prior. That way this parameter is always updated by the information in the data likelihood. The choice of a Gamma prior for $(\tau_{j,t}^2)^{-1}$ implies that the marginal prior for $\beta_{j,t}$ is a mixture of leptokurtic Student's T distributions whose components could tend to shrink $\beta_{j,t}$ towards zero, regardless of whether $\gamma_{j,t}$ is zero or one. Therefore, the proposed prior is able to find patterns of dynamic sparsity as well as impose dynamic shrinkage in time-varying parameters, a property that is very desirable in high-dimensional settings.⁸

Finally, it becomes apparent that under this variable selection prior setting, $\widehat{\pi}_{0,t} = \mathbb{E}\left(p\left(\pi_{0,t}\right)\right) = \frac{1}{2}$ is the time t prior mean probability of inclusion of all predictors in the TVP regression, while the quantity $\widetilde{\pi}_{j,t} = \mathbb{E}\left(p\left(\gamma_{j,t}|\mathbf{y}_{1:T}\right)\right)$ is the posterior mean probability of inclusion in the regression of predictor j at time period t, simply referred to as the posterior inclusion probability (PIP). Due to the fact that all of the hyperparameters γ , π and τ^2 are time-varying, our prior allows to obtain time-varying PIPs whose interpretation extends this of PIPs in constant parameter settings, such as the one in George and McCulloch (1993), in a straightforward way.

In terms of tackling estimation using this prior we note that adding the prior (22) to our benchmark TVP specification introduces some peculiarity: by combining equations (10) and (22) we end up having two conditional prior structures for $\beta_{j,t}$, namely

$$\beta_{j,t}|\beta_{j,t-1}, w_{j,t} \sim N(\beta_{j,t-1}, w_{j,t})$$
(26)

$$\beta_{j,t}|\gamma_{j,t},\tau_{j,t}^2 \sim N(0,v_{j,t}), \qquad (27)$$

where we define $v_{j,t} = (1 - \gamma_{j,t})^2 \underline{c} \times \tau_{j,t}^2 + \gamma_{j,t}^2 \tau_{j,t}^2$ and V_t is the $p \times p$ diagonal matrix comprising the elements $v_{j,t}$. Following ideas in Wang et al. (2016) we combine the two priors for β_t described above by rewriting the state equation as⁹

$$\boldsymbol{\beta}_t = \widetilde{\boldsymbol{F}}_t \boldsymbol{\beta}_{t-1} + \widetilde{\boldsymbol{\eta}}_t, \tag{28}$$

⁸In signal processing a signal (regression coefficient vector) is typically sparse by default, that is, the researcher knows a-priori to expect that estimates of several coefficients will tend to be exactly zero. In economics, the sparsity assumption might not be empirically founded in certain settings; see the discussion in Giannone et al. (2017). In such cases, a dense model may be preferred, that is, a model where all predictors are relevant with varying weights. While factor models and principal components have been used widely to model dense models in macroeconomics, shrinkage methods are also quite reliable for this task. In particular, we note the result in De Mol et al. (2008) that forecasts from Bayesian shrinkage are highly correlated to forecasts from principal components.

⁹The derivation is straightforward using arguments in the previous subsection, see equation (19). Define

where $\widetilde{\boldsymbol{\eta}}_t \sim N\left(\mathbf{0}, \widetilde{\boldsymbol{W}}_t\right)$, with parameter matrices $\widetilde{\boldsymbol{W}}_t = \left(\mathbb{E}\left(\boldsymbol{W}_t\right)^{-1} + \mathbb{E}\left(\boldsymbol{V}_t\right)^{-1}\right)^{-1}$ and $\widetilde{\boldsymbol{F}}_t = \widetilde{\boldsymbol{W}}_t \times \mathbb{E}\left(\boldsymbol{W}_t\right)^{-1}$, where $\boldsymbol{W}_t = diag\left(w_{1,t},...,w_{p,t}\right)$ and $\boldsymbol{V}_t = diag\left(v_{1,t},...,v_{p,t}\right)$, and all expectation operators are with respect to $q\left(\boldsymbol{\beta}_t|\boldsymbol{y}_{1:t}\right)$. Under this formulation we can observe that the joint prior variance for $\beta_{j,t}$ is a function of both $w_{j,t}$ and $v_{j,t}, \forall j = 1,...,p$. Therefore, the TVP regression model with dynamic variable selection prior can be written using a new state-space form, with measurement equation given by (9) and state equation given by (28).

Application of algorithm 1 to the transformed state-space model consisting of equations (20) and (28) provides as output estimates $m_{t|T} \, \forall t$, that is, the smoothed posterior mean of $q(\beta_t|y_{1:T})$. Conditional on these estimates, derivation of the update steps for $\gamma_{j,t}$, $\tau_{j,t}^2$ and $\pi_{0,t}$ relies also on deriving the expectations of these variables with respect to $q(\beta_t|y_{1:T})$. Therefore, extending the analysis of the previous section to accommodate these new parameters, and similar to derivations found in Gibbs sampling approaches to variable selection (see, for instance, the formulas of the conditional posteriors in George and McCulloch, 1993), the updating steps for the parameters in the dynamic variable selection prior are the following

$$\widehat{\tau}_{i,t}^{2} = \mathbb{E}\left[q\left(\tau_{i,t}^{2}|y_{t}\right)\right] = \left(h_{0} + m_{i,t|T}^{2}\right) / \left(g_{0} + 1/2\right),\tag{29}$$

$$\widehat{\gamma}_{j,t} = \mathbb{E}\left[q\left(\gamma_{j,t}|y_{t}\right)\right] = \frac{N\left(m_{j,t|T}|0,\widehat{\tau}_{j,t}^{2}\right)\widehat{\pi}_{0,t}}{N\left(m_{j,t|T}|0,\widehat{\tau}_{j,t}^{2}\right)\widehat{\pi}_{0,t} + N\left(m_{j,t|T|t}|0,\underline{c}\times\widehat{\tau}_{j,t}^{2}\right)(1-\widehat{\pi}_{0,t})}, \quad (30)$$

$$\widehat{v}_{j,t} = \mathbb{E}\left[q\left(v_{j,t}|y_t\right)\right] = \left(1 - \widehat{\gamma}_{j,t}\right)^2 \underline{c}\widehat{\tau}_{j,t}^2 + \widehat{\gamma}_{j,t}\widehat{\tau}_{j,t}^2, \tag{31}$$

$$\widehat{\pi}_{0,t} = \mathbb{E}\left[q\left(\pi_{0,t}|y_t\right)\right] = \left(1 + \sum_{j=1}^p \widehat{\gamma}_{j,t}\right) / (2+p), \tag{32}$$

for each t = 1, ..., T and j = 1, ..., p, where again expectations \mathbb{E} are with respect to the VB posteriors of each of the parameters showing up on the right-hand side of the equations above.

 $q(\beta_t|y_{1:t-1})$ to be the time t variational Bayes prior of β_t given information at time t-1. Then we have

$$q\left(\boldsymbol{\beta}_{t}|\boldsymbol{y}_{1:t-1}\right) \propto \exp\left\{\mathbb{E}\left(\log p\left(\boldsymbol{\beta}_{t}|\boldsymbol{\beta}_{t-1},\boldsymbol{W}_{t}\right)\right) + \mathbb{E}\left(\log p\left(\boldsymbol{\beta}_{t}|\boldsymbol{V}_{t}\right)\right)\right\}$$

$$\propto \exp\left\{-\frac{1}{2}\left(\boldsymbol{\beta}_{t}-\boldsymbol{\beta}_{t-1}\right)'\boldsymbol{W}_{t}^{-1}\left(\boldsymbol{\beta}_{t}-\boldsymbol{\beta}_{t-1}\right) - \frac{1}{2}\boldsymbol{\beta}_{t}'\boldsymbol{V}_{t}^{-1}\boldsymbol{\beta}_{t}\right\}$$

$$\propto \exp\left\{-\frac{1}{2}\boldsymbol{\beta}_{t}'\boldsymbol{W}_{t}^{-1}\boldsymbol{\beta}_{t} + \boldsymbol{\beta}_{t}'\boldsymbol{W}_{t}^{-1}\boldsymbol{\beta}_{t-1} - \frac{1}{2}\boldsymbol{\beta}_{t}'\boldsymbol{V}_{t}^{-1}\boldsymbol{\beta}_{t}\right\}$$

$$\propto \exp\left\{-\frac{1}{2}\left(\boldsymbol{\beta}_{t}-\widetilde{\boldsymbol{F}}_{t}\boldsymbol{\beta}_{t-1}\right)'\widetilde{\boldsymbol{W}}_{t}^{-1}\left(\boldsymbol{\beta}_{t}-\widetilde{\boldsymbol{F}}_{t}\boldsymbol{\beta}_{t-1}\right)\right\},$$

where the simplification occurs due to the fact that β_{t-1} is known and fixed (i.e. not a random variable) given information at time t-1. Therefore, the formula above specifies the new, joint time t prior of β_t given the two priors in equations (26)-(27).

3.2 Adding stochastic volatility

A known regression variance is far from a realistic assumption for most datasets. When forecasting macroeconomic data, so is the assumption of an unknown variance that is constant over time. A vast recent literature highlights the importance of time-varying volatility in improving point and density forecasts (Clark and Ravazzolo, 2015), and the purpose of this subsection is to accommodate estimation of the parameter $var(\varepsilon_t) = \sigma_t^2$ in the VB setting. Several elegant algorithms for VB inference in stochastic volatility models exist in the literature. For example, Naesseth et al. (2017) introduce a variational Bayes Sequential Monte Carlo (SMC) algorithm for stochastic volatility models. Tran et al. (2017) propose a variational Bayes method for intractable likelihoods that does not rely on the mean field approximation, and apply their algorithm to the estimation of a stochastic volatility model.

Nevertheless, such algorithms assume an explicit time-series model for the stochastic volatility parameter, an assumption that is only useful in a setting where one is interested in forecasting volatility. In a macroeoconomic setting we are interested in forecasting y_t and not its volatility (as it would be the case in empirical asset pricing). At the same time, previous empirical work shows that there are no statistically important differences when forecasting with alternative specifications of macroeconomic volatility. For that reason, our aim here is not only to render estimation of stochastic volatility precise, but at the same time numerically reliable and computationally efficient. In order to achieve this, we build on variance discounting ideas for dynamic linear methods as described in West and Harrison (1997); see also Ročková and McAlinn (2017).

Define $\phi_t = \frac{1}{\sigma_t^2}$ to be the precision (inverse variance). Following West and Harrison (1997) we assume that the time t-1 posterior of ϕ has the following conjugate form

$$\phi_{t-1}|y_{1:t-1} \sim Gamma(a_{t-1}, b_{t-1}).$$
 (33)

We do not specify an explicit time series model for the dynamics of ϕ (e.g. stochastic volatility or GARCH) because the posterior for ϕ_t wouldn't be conjugate to the likelihood and we would fail to obtain fast updates. In order to maintain this conjugacy we specify instead the time t prior of the form

$$\phi_t | y_{1:t-1} \sim Gamma\left(\delta a_{t-1}, \delta b_{t-1}\right), \tag{34}$$

¹⁰For example, Clark and Ravazzolo (2015) compare a range of specifications for time-varying variance parameters in univariate and multivariate autoregressive models, and any differences among such specifications are not statistically important (while all volatility specifications are always better relative to constant variance specifications).

for a variance discounting factor $0 < \delta < 1$, subject to a choice of hyperparameters a_0 and b_0 . By doing so, we assume that ϕ_t is centered around ϕ_{t-1} as if this parameter had random walk dynamics,¹¹ since it holds that $\mathbb{E}(\phi_t|y_{1:t-1}) = \mathbb{E}(\phi_{t-1}|y_{1:t-1})$. However, based on the properties of the Gamma distribution, the dispersion of ϕ_t is larger to that of ϕ_{t-1} .

Under this scheme the variational Bayes update of ϕ_t , that is, its time t posterior mean has the form

$$\widehat{\phi}_t = \mathbb{E}_{q(\beta_t|y_{1:T})}\left(\phi_t|y_{1:t}\right) = a_t/b_t,\tag{36}$$

where $a_t = 1/2 + \delta a_{t-1}$ and $d_t = \frac{1}{2} \left[\left(y_t - \boldsymbol{x}_t \boldsymbol{m}_{t|T} \right) \right]^2 + \boldsymbol{x}_t \boldsymbol{P}_{t|T} \boldsymbol{x}_t' + \delta b_{t-1}$, where $\boldsymbol{m}_{t|T}, \boldsymbol{P}_{t|T}$ are the smoothed mean and variance of β_t . Using this scheme, past information in the data is discounted exponentially by the factor δ . The scalar δ can be seen as a prior hyperparameter whose choice determines how much relative weight we give to recent versus older observations, that is, it determines how fast we expect the precision parameter to change over time. For $\delta = 1$ we obtain the posterior under a standard recursive update scheme (similar to recursive OLS), while typical values that would allow for faster time-variation in the precision/variance would be between 0.8 and 0.99. Values lower than 0.8 are not empirically advised, since they allow for a large amount of time-variation and stochastic variance estimates become very noisy. In the empirical exercise we set $\delta = 0.8$, a choice that reflects our prior expectation that macroeconomic data have many abrupt breaks in their second moments and excess kurtosis during recessions (implying variances that can move very fast over time).

The previous formulas pertain to the iterative updating of ϕ_t given ϕ_{t-1} . Estimates of ϕ_t can be smoothed using subsequent observations t+1,...,T. Following West and Harrison (1997) we can run a backward recursive filter of the form

$$\widetilde{\phi}_t = (1 - \delta)\widehat{\phi}_t + \delta\widetilde{\phi}_{t+1},\tag{37}$$

for t = T - 1, ..., 1, where $\widetilde{\phi}_t = \mathbb{E}_{q(\beta_t|y_{1:T})} (\phi_t|y_{t+1})$ and $\widetilde{\phi}_T = \widehat{\phi}_T$. Once we obtain this update for the precision ϕ_t , a posterior mean estimate of the volatility σ_t^2 can be obtained simply as the inverse of $\widetilde{\phi}_t$.

$$\phi_t = \gamma_t \phi_{t-1} / \delta, \tag{35}$$

for a parameter $\gamma_t | y_{1:t-1} \sim Beta\left(\delta a_{t-1}/2, (1-\delta)a_{t-1}/2\right)$.

¹¹Even though we haven't specified an explicit time series evolution for ϕ_t , by using results in Uhlig (1994) we can show that the proposed variance discounting methodology is equivalent to assuming the following specification:

3.3 The Variational Bayes Dynamic Variable Selection (VBDVS) algorithm

Here we provide details of the exact parameter updates that result from VB inference in our proposed specification. Algorithm 2 outlines our proposed Variational Bayes Dynamic Variable Selection (henceforth, VBDVS) algorithm. This Algorithm shows an accurate picture of how this would look like when programmed using a language like MATLAB or R: while there are many parameters involved in our specification, the code is short and it involves simple scalar operations (meaning it is very fast). The only cumbersome operation is the inversion of the $p \times p$ matrix $P_{t+1|t}$ in line 14 which has worst case complexity $6(p^3)$ for each t. There are four main blocks in this algorithm. Lines 4-12 are a result of straightforward application of the Kalman filter on the state-space model of equations (20) and (28), and lines 13-17 show the backwards (smoothing) recursions. Lines 18-27 update the prior hyperparameters of the DVS prior for β_t . Finally, lines 28-33 provide updates for the stochastic volatility parameter, as discussed in the previous subsection.

4 Simulation study

In this section we evaluate the performance of the new estimator using artificial data. Although we view the algorithm as primarily a forecasting algorithm, it is also important to investigate its estimation accuracy in an environment where we know the true data generating process (DGP). Thus, we wish to to establish that the VBDVS is able to track time-varying parameters satisfactorily and establish that the dynamic variable selection prior is able to perform shrinkage and selection with high accuracy (at least in cases where we know that the DGP is that of a sparse TVP regression model). We also wish to investigate the computational gains that arise from application of variational Bayes methods on the complex dynamic variable selection prior structure.

In all our experiments we use the following DGP:

$$y_t = \beta_{1t}x_{1t} + \beta_{2t}x_{2t} + \dots + \beta_{nt}x_{nt} + \sigma_t\varepsilon_t, \ \varepsilon_t \sim N(0, 1)$$
(38)

$$x_{j,t} \sim N(0,1), \ j=1,...,p$$
 (39)

$$\beta_{j,t} = s_{j,t} \times \theta_{j,t} \tag{40}$$

$$\theta_{j,t} = \underline{\theta}_j + \rho \left(\theta_{j,t-1} - \underline{\theta}_j \right) + \underline{\delta} \eta_{j,t}, \ \eta_{j,t} \sim N(0,1)$$
(41)

$$\log\left(\sigma_t^2\right) = \underline{\sigma}^2 + \underline{\phi}\left(\log\left(\sigma_{t-1}^2\right) - \underline{\sigma}^2\right) + \underline{\xi}\zeta_t, \ \zeta_t \sim N(0, 1)$$
(42)

$$\theta_{j,0} = \underline{\theta}_j, \quad \log(\sigma_0^2) = \underline{\sigma}^2.$$
 (43)

Algorithm 2 Variational Bayes algorithm for TVP regression model with dynamic variable selection and stochastic variance (VBDVS algorithm)

```
1: Choose values of m_0, P_0, a_0, b_0, c_{j,0}, d_{j,0}, g_0, h_0, \underline{c}, and \delta; initialize all vectors/matrices.
 3: while \|\mathscr{G}\left(q(\boldsymbol{\beta}^{(r)}, \boldsymbol{w}^{(r)}|\boldsymbol{y}\right) - \mathscr{G}\left(q(\boldsymbol{\beta}^{(r-1)}, \boldsymbol{w}^{(r-1)}|\boldsymbol{y}\right)\| \to 0 \text{ do}
                       \begin{aligned} & \text{for } t = 1 \text{ to } T \text{ do} \\ & \widetilde{\boldsymbol{W}}_{t}^{(r)} = diag \left( \left( w_{1,t}^{-1} \right. \left. \left( r-1 \right) + v_{1,t}^{-1} \right. \left. \left( r-1 \right) \right)^{-1}, ..., \left( w_{p,t}^{-1} \right. \left. \left( r-1 \right) + v_{p,t}^{-1} \right. \left( r-1 \right) \right)^{-1} \right) \end{aligned} 
 4:
                                \widetilde{\boldsymbol{F}}_{t}^{(r)} = \widetilde{\boldsymbol{W}}_{t}^{(r)} \left( \boldsymbol{W}_{t}^{(r-1)} \right)^{-1}
 6:
                               m{m}_{t|t-1}^{(r)} = \widetilde{m{F}}_t^{(r)} m{m}_{t-1|t-1}^{(r)}
 7:
                                                                                                                                                                                                                                                                                                                                                    Predicted mean
                                \boldsymbol{P}_{t|t-1}^{(r)} = \widetilde{\boldsymbol{F}}_t^{(r)} \boldsymbol{P}_{t-1|t-1} \widetilde{\boldsymbol{F}}_t^{(r)'} + \widetilde{\boldsymbol{W}}_t^{(r)}
                                                                                                                                                                                                                                                                                                                                      Predicted variance
                               egin{align*} m{K}_{t}^{(r)} &= m{P}_{t|t-1}^{(r)} m{x}_t' \left(m{x}_t m{P}_{t|t-1}^{(r)} m{x}_t' + \widehat{\sigma}_t^{2} m{r-1}
ight)^{-1} \ m{m}_{t|t}^{(r)} &= m{m}_{t|t-1}^{(r)} + m{K}_t^{(r)} \left(y_t - m{x}_t m{m}_{t|t-1}^{(r)}
ight) \ m{P}_{t|t}^{(r)} &= \left(m{I}_p - m{K}_t^{(r)} m{x}_t
ight) m{P}_{t|t-1}^{(r)} \end{aligned}
                                                                                                                                                                                                                                                                                                                                                               Kalman gain
10:
                                                                                                                                                                                                                                                                                                                                  Filtered mean of \beta_t
11:
                                                                                                                                                                                                                                                                                                                    Filtered variance of \beta_t
                      end for for T=T-1 to 1 do C=P_{t|t}^{(r)}\widetilde{F}_{t}^{(r)}\left(P_{t+1|t}^{(r)}\right)^{-1}
12:
13:
14:
                                 egin{array}{ll} m{m}_{t|T}^{(r)} &= m{m}_{t|t}^{(r)} + C\left(m{m}_{t+1|T}^{(r)} - m{m}_{t+1|t}^{(r)}
ight) \\ m{P}_{t|T}^{(r)} &= m{P}_{t|t}^{(r)} + C\left(m{P}_{t+1|T}^{(r)} - m{P}_{t+1|t}^{(r)}
ight) m{C}' \end{array}
15:
                                                                                                                                                                                                                                                                                                                                  Smoothed mean of oldsymbol{eta}_t
16:
                                                                                                                                                                                                                                                                                                                     Smoothed variance of \beta_t
17:
                       m{D}_t = m{P}_{t|T}^{(r)} + m{m}_{t|T}^{(r)} m{m}_{t|T}^{(r)'} + \left(m{P}_{t-1|T}^{(r)} + m{m}_{t-1|T}^{(r)} m{m}_{t-1|T}^{(r)'}
ight) \left(I_p - 2\widetilde{F}_t^{(r)}
ight)'
18:
                                                                                                                                                                                                                                                                                                          Squared error in state eq.
                        R_t = \left[ \left( y_t - \boldsymbol{x}_t \boldsymbol{m}_{t|T}^{(r)} \right)^2 + \boldsymbol{x}_t \boldsymbol{P}_{t|T} \boldsymbol{x}_t' \right]
19:
                                                                                                                                                                                                                                                                                     Squared error in measurement eq.
20:
                         for t = 1 to T do
                                \begin{split} \mathbf{r} & t = 1 \text{ to } T \text{ do} \\ & \text{for } j = 1 \text{ to } p \text{ do} \\ & \widehat{\tau}_{j,t}^{-2} \overset{(r)}{=} (g_0 + 0.5) \, / \left( h_0 + 0.5 \left( m_{j,t|T}^{(r)} \right)^2 \right) \\ & \widehat{\gamma}_{j,t}^{(r)} = \frac{N \left( m_{j,t|T}^{(r)} | 0, \widehat{\tau}_{j,t}^2 ^{(r)} \right) \widehat{\pi}_{0,t}^{(r-1)}}{N \left( m_{j,t|T}^{(r)} | 0, \widehat{\tau}_{j,t}^2 ^{(r)} \right) \widehat{\pi}_{0,t}^{(r-1)} + N \left( m_{j,t|T|t}^{(r)} | 0, \underline{c} \times \widehat{\tau}_{j,t}^2 ^{(r)} \right) \left( 1 - \widehat{\pi}_{0,t}^{(r-1)} \right)} \\ & \widehat{v}_{j,t}^{(r)} = \left( 1 - \widehat{\gamma}_{j,t}^{(r)} \right)^2 \underline{c} \widehat{\tau}_{j,t}^2 \overset{(r)}{\tau} + \widehat{\gamma}_{j,t}^{(r)} \widehat{\tau}_{j,t}^2 \overset{(r)}{\tau} \\ & \widehat{w}_{j,t}^{-1} \overset{(r)}{=} (\underline{c}_0 + 0.5) \, / \left( \underline{d}_0 + 0.5 \boldsymbol{D}_{jj,t} \right) \end{split}
21:
                                                                                                                                                                                                                                                                                                                          Posterior mean of \frac{1}{\tau_{i,t}^2}
22:
23:
                                                                                                                                                                                                                                                                                                                           Posterior mean of \gamma_{i,t}
                                                                                                                                                                                                                                                                                                                            Posterior mean of v_{i,t}
25:
                                                                                                                                                                                                                                                                                                                         Posterior mean of \frac{1}{w_{i,t}}
                                   end for \widehat{\pi}_{0,t}^{(r)} = \left(1 + \sum_{j=1}^p \widehat{\gamma}_{j,t}^{(r)}\right)/(2+p)
27:
                                                                                                                                                                                                                                                                                                                          Posterior mean of \pi_{0,t}
28:
                                   \widehat{\phi}_t^{(r)} = (\delta a_{t-1} + 0.5) / (\delta b_{t-1} + 0.5 R_t)
                                                                                                                                                                                                                                                                                                                                Filtered mean of \frac{1}{\sigma_{\star}^2}
29:
                         end for
                         for T = T - 1 to 1 do
\widetilde{\phi}_t^{(r)} = (1 - \delta)\widehat{\phi}_t^{(r)} + \delta\widetilde{\phi}_{t+1}^{(r)}
30:
                                                                                                                                                                                                                                                                                                                                Smoothed mean of \frac{1}{\sigma^2}
31:
32:
                         end for
33:
34: end while
```

Our benchmark specification sets $\underline{\theta} = (-1.7, 2.9, 1.4, -2.3, \mathbf{0}), \ \underline{\sigma}^2 = 0.1, \ \underline{\rho} = \underline{\phi} = 0.99, \ \underline{\delta} = \underline{\xi} = T^{-1/2}$. In the specification above s_j is $T \times 1$ vector of either zeros or ones, such that $\beta_{j,t} = \theta_{j,t}$ when $s_{j,t} = 1$, and zero otherwise. We set $s_{1,t} = 1$ for $t = 1, ..., \lfloor T/3 \rfloor - 1$ and zero otherwise, $s_{2,t} = 1 \ \forall t = 1, ..., T$, $s_{3,t} = 1$ for $t = 1, ..., \lfloor T/2 \rfloor - 1$ and zero otherwise, $s_{4,t} = 0$ for $t = 1, ..., \lfloor T/2 \rfloor - 1$ and zero otherwise. These choices mean that $\beta_{1,t}$ is zero during the last third of the sample, $\beta_{2,t}$ is a relevant predictor in all periods, $\beta_{3,t}$ is zero during the last half of the sample, and $\beta_{4,t}$ is zero during the first half of the sample. Any other coefficient for j = 5, ..., p is zero at all periods, i.e. $s_{j,t} = 0 \ \forall \ j > 4, \ t = 1, ..., T$. By doing so, we simulate a situation where only one predictor is relevant in all time periods, three predictors are relevant only in certain subsamples of the data, and all remaining p - 4 predictors are irrelevant for y at all time periods.

After we generate artificial data, we compare three competing estimation algorithms for TVP models: i) our variational Bayes dynamic variable selection (VBDVS) algorithm, ii) the EM algorithm implementation of the dynamic spike and slab (DSS) of Ročková and McAlinn (2017), and iii) Gibbs sampling (MCMC) estimation of the TVP model using the fast algorithm of Chan and Jeliazkov (2009). While there are numerous other algorithms available for estimating TVP models, our limited choice of algorithms reflects our desire to simulate exclusively high-dimensional models. By doing so, we exclude most of the recently proposed Bayesian methodologies cited in the Introduction. These methodologies introduce various flexible parametrizations (like we do) that result, however, in the need for many tuning parameters and estimation via MCMC, such that they become unreasonably cumbersome for p > 50. Our model instead, as we demonstrate in detail later, requires very straightforward tuning. The default prior setting we use for the VBDVS algorithm is based on the case Prior 3 presented in Table 2 in the next section. The settings used in the DSS and MCM algorithms are discussed in the Online Supplement to this paper. In order to compare numerically these algorithms we generate R=100 datasets from the above DGP for various choices of sample size and total number of predictors, namely T = 100, 200, 500 and p = 50, 100, 200. Subsequently squared deviations between true and estimated parameters are calculated, and then averaged over the T time periods, and p predictors. To be precise, if we let (β_t^{true}) denote the true artificially generated coefficients and (β_t^j, σ_t^j) , for j = DVS, DSS, MCMC, the estimates of these coefficients, we calculate the sum of mean squared deviations (MSD) statistic as

$$MSD_{\beta}^{j} = \sum_{r=1}^{100} \left(\frac{1}{T \times p} \sum_{t=1}^{T} \sum_{i=1}^{p} \left(\beta_{it}^{true,(r)} - \beta_{it}^{j,(r)} \right)^{2} \right), \tag{44}$$

where r = 1, ..., 500 denotes the number of Monte Carlo iterations.

Time-varying coefficient estimates

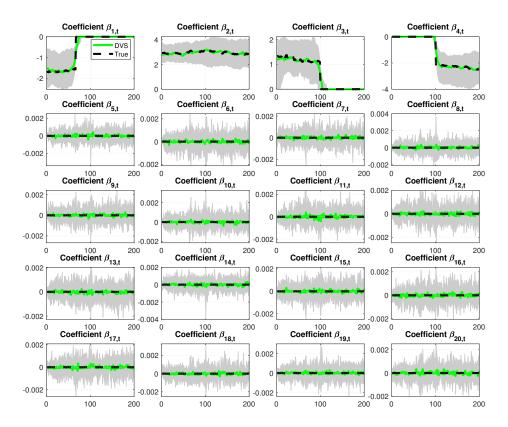


Figure 1: VBDVS coefficient estimates of the first 20 predictors generated from the DGP with T=200 and p=200. Black dashed lines are the true generated coefficients. Posterior medians (over the 100 Monte Carlo iterations) of VBDVS estimates are shown with green solid lines, and grey areas denote 16^{th} and 84^{th} percentiles.

Time-varying inclusion probabilities

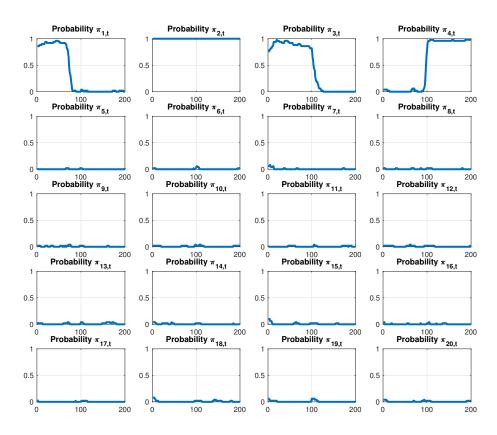


Figure 2: Time-varying posterior inclusion probabilities (expected value of $\gamma_{j,t}$ estimates) of the first 20 predictors generated from the DGP with T = 200 and p = 200. These probabilities are means over the 100 Monte Carlo iterations.

Figure 1 shows the coefficient estimates from VBDVS for the case T=p=200. This plot compares the posterior median (green solid lines) versus the true generated coefficients (black dashed lines). The 16^{th} and 84^{th} percentiles over the 100 Monte Carlo iterations are also shown as a shaded area around the posterior median. Only the first 20 coefficients, out of the possible 200, are plotted. The first row shows the four coefficients that, at least in some periods, are non-zero, followed by 16 coefficients that are exactly zero. It is impossible to plot the remaining 180 coefficients in the DGP that are exactly zero, but their estimates are represented fairly well by the estimates of coefficients $\beta_{5,t}$ - $\beta_{20,t}$ shown in Figure 1. Under the assumption of sparsity in the DGP, the VBDVS algorithm is able to recover the true coefficients with accuracy. Not only the coefficients that are zero in the DGP in all periods are correctly estimated to be zero, but also the three coefficients that are zero only in certain subsamples are estimated precisely. When a coefficient is initially zero and later in the sample becomes important (see coefficient $\beta_{4,t}$), and vice-versa (see coefficients $\beta_{1,t}$ and $\beta_{3,t}$), the dynamic variable selection algorithm is able to identify and jump quickly to

the new state. Figure 2 shows that the true reason why estimation is so precise – even in such a demanding case with 200 time-varying coefficients for only 200 observations – is because the estimates of the time-varying posterior inclusion probabilities (PIPs) of each predictor are recovered with precision in the first instance. By identifying correctly which variables should be excluded from the regression model in each period results in shrinking many coefficients to zero and allowing to preserve enough degrees of freedom for estimation of non-zero coefficients.

Table 1 shows the values of the MSD statistics for the three algorithms under the different combinations of T and p. Given that the MSD statistics measure deviation from the true coefficient, lower values imply that a certain estimation algorithm has done better recovery of the coefficients generated by the DGP. In all cases VBDVS has the best performance among all competing algorithms. The estimation error of the MCMC algorithm is quite large mainly because the algorithm is unable to shrink all p-4 coefficients in the DGP that are exactly zero. The DSS algorithm provides a better fit since it is also an algorithm that does dynamic variable selection and shrinkage. Its performance is slightly inferior to VBDVS, but the results should not be taken as final evidence. While we have done all effort to follow the settings suggested by Ročková and McAlinn (2017), there might be other priors that could improve the performance of this algorithm.

Another important feature of the VBDVS algorithm is its fast computing time. While it is not surprising that our algorithm is faster compared to MCMC, our algorithm can provide substantial savings in high-dimensional settings compared to the DSS that relies on the EM algorithm. Columns 6-8 in Table 1 reveals that VBDVS can be multiple times faster than both DSS and MCMC algorithms.

Table 1: MSD	statistics and	d computing	time for	Monte	Carlo	exercise

		MS	D statis	stic	Comput	Computing time (secs)				
		VBDVS	DSS	MCMC	VBDVS	DSS	MCMC			
	p = 50	0.203	0.419	7.979	1.2	8.3	22.6			
T = 100	p = 100	0.469	1.014	11.787	7.2	20.1	106.6			
	p = 200	0.536	1.915	14.628	29.9	45.8	402.0			
T = 200	p = 50	0.047	0.256	5.825	5.5	19.9	49.9			
	p = 100	0.088	0.789	10.583	10.1	40.1	232.2			
	p = 200	0.165	1.780	17.983	38.6	91.9	841.4			
	p = 50	0.019	0.147	4.613	8.3	51.1	125.2			
T = 500	p = 100	0.043	0.819	9.095	50.9	125.1	555.6			
	p = 200	0.085	1.679	18.398	83.6	220.6	2127.8			

Notes: Computing times are based on a Windows 10 laptop running MATLAB 2020a, featuring an Intel i7-8665U processor and 32GB of RAM.

5 Macroeconomic Forecasting with Many Predictors

5.1 A new large dataset for forecasting inflation

Following a large literature on time-varying parameter models in macroeconomics, our primary target is to forecast quarterly US inflation. While there exists mixed empirical evidence about the potential of very large datasets to improve forecasts of inflation, our aim is to demonstrate here that the new dynamic variable selection methodology can successfully extract, period-by-period, predictive information from a large number of predictors. For that reason we build a novel, high-dimensional dataset that brings together predictors from several mainstream aggregate macroeconomic and financial datasets. Our building block is the FRED-QD dataset of McCracken and Ng (2020), which we augment with portfolio data used in Jurado et al. (2015), stock market predictors from Welch and Goyal (2007), survey data from University of Michigan consumer surveys, commodity prices from the World Bank's Pink Sheet database, and key macroeconomic indicators from the Federal Reserve Economic Data for four economies (Canada, Germany, Japan, UK). All data are quarterly, and span the period 1960Q1-2018Q4. All variables are adjusted from their respective sources for seasonality (where relevant), and we additionally remove extreme outliers.

¹²While one could also think of potential predictors in disaggregated panels obtained in surveys, internet, or documents (text data), such novel sources are typically proprietary and would make our results hard to replicate.

¹³Following Stock and Watson (2016), we replace outliers using the median of the preceding five observations. An outlier is defined to be any observation that satisfies $|y_t - m|/iqr > \kappa$, where m is

The dataset has in total 444. Out of these we forecast the series (FRED-QD mnemonics in parentheses): GDP deflator (GDPCTPI), total CPI (CPIAUCSL), core CPI (CPILFESL), and PCE deflator (PCECTPI). When each of these price series, P_t , is used as the dependent variable to be forecasted h-quarters ahead we transform it according to the formula $y_{t+h} = (400/h) \ln (P_{t+h} - P_t)$. We forecast these transformed series one at a time, and the remaining three price series are included in the list of exogenous predictor variables (443 in total). The predictor variables are transformed using standard norms in the literature (see for example McCracken and Ng, 2020): i) levels for variables that are already expressed in rates (e.g. unemployment, interest); ii) first differences of logarithm for variables measuring population (e.g. employment), variables expressed in dollars (e.g. GDP), commodity prices, and some indexes (e.g. Industrial production); and iii) second differences of logarithm for price and consumption indexes, as well as deflator series. The online supplement describes in detail all variables and transformations, and provides links to all sources.

5.2 How the dynamic variable selection algorithm works: An insample assessment

Before we set up a comprehensive out-of-sample forecasting exercise, we first assess in-sample estimates from the VBDVS by doing small sensitivity analysis to various prior choices. This exercise is intended to demonstrate that the new algorithm provides reasonable estimates of trends, volatilities and other parameters. Most importantly it serves as a way to clarify that, despite the fact that our prior is heavily parametrized, prior elicitation in the VBDVS algorithm becomes a reasonably straightforward task. As it is impossible to present estimates of the TVP model using all variables in our dataset as predictors, we focus on a small TVP model where GDP deflator regressed on an intercept, two own lags, and the first five principal components from the 443 exogenous predictors (eight predictors in total).

Out of all parameters and hyperparameters defined in our algorithm it is only a handful that are crucial for inference and forecasting, while others can be fixed to reasonable or uninformative values and possibly have little effect on forecasting. Table 2 lists all hyperparameters one need to choose in the VBDVS algorithm, and does an explicit separation into "Important" and "Fixed" hyperparameters. Starting from the latter, a_0 and b_0 are the initial scale and rate parameters of the initial condition of the precision parameter in equation (34). Setting $a_0 = b_0 = 0.01$ implies that the precision has prior mean one and variance 10, which is a reasonable uninformative choice for an inverse variance parameter. Next, we set $\delta = 0.8$ for reasons explained in subsection 3.2. Given that p is very large to allow us to

the median of y, iqr is the interquantile range, and $\kappa = 4.5$.

obtain meaningful prior information about the regression coefficients β_t (e.g. using a training sample), we allow their initial condition β_0 to be fairly uninformative by setting $m_0 = 0$ and $P_0 = 4I_p$. The parameter \underline{c} in the dynamic variable selection prior has to be small (see discussion in subsection 3.1) and how small it exactly is, affects the way the algorithm selects each of the two Normal components in the spike and slab prior – that is, it affects the choice between a certain $\beta_{j,t}$ being restricted or not. We prefer to fix this parameter to $\underline{c} = 0.0001$ and allow only $\tau_{j,t}^2$ and its prior to determine the ratio of the prior variances of the two Normal components in the mixture prior.

Table 2: Hyperparameter choices for sensitivity analysis

	Prior 1	Prior 2	Prior 3	Notes
IMPO	RTANT H			
g_0	0.01	0.01	1	see eq. (24)
h_0	0.01	0.01	12	see eq. (24)
$c_{j,0}$	100	1	100	see eq. (11)
$d_{j,0}$	1	1	1	see eq. (11)
FIXE		PARAMET		
\underline{c}	10^{-4}	10^{-4}	10^{-4}	see eq. (22)
a_0	0.01	0.01	0.01	see eq. (34)
b_0	0.01	0.01	0.01	see eq. (34)
δ	0.8	0.8	0.8	see eq. (34)
$m_{j,0}$	0	0	0	see eq. (11)
$P_{j,0}$	4	4	4	see eq. (11)

The parameters that are important in our high-dimensional setting are the ones affecting the two prior variances of the time-varying coefficients β_t , namely the hyperparameters of $\tau_{j,t}^2$ and $w_{j,t}$. Our first prior choice, denoted as "Prior 1" in Table 2, selects $c_{j,t} = 100$, $d_{j,t} = 1$ such that $w_{j,t}$ has a prior mean of 0.01 and prior variance 0.0001. This conservative choice restricts movements $\beta_{j,t}$ to be very persistent and excludes the case of frequent, noisy jumps. Such prior is used widely in empirical macroeconomic applications, see for example the "business as usual" prior motivated in Cogley and Sargent (2005) for the case of a vector autoregression with time-varying parameters. We subsequently set an uninformative prior on $\tau_{j,t}^2$ by setting $g_0 = h_0 = 0.01$. The dashed lines in Figure 3 represent (posterior mean) coefficient estimates from our eight-predictor model: coefficient $\beta_{1,t}$ is the time-varying intercept (trend inflation), coefficients $\beta_{2,t}$, $\beta_{3,t}$ correspond to the first two lagged values of GDP deflator, and coefficients $\beta_{4,t}$ to $\beta_{8,t}$ correspond to the five principal components. As a comparison, we plot posterior mean estimates from the same time-varying parameter regression estimated with MCMC (using identical settings as in the Monte Carlo comparison). The MCMC-based estimates can be broadly thought of as the unrestricted equivalents of the VBDVS algorithm, since

they are not based on any form of dynamic variable selection or hierarchical shrinkage. The intercept and first lag coefficients are virtually identical using the two algorithms. However, all remaining coefficients are penalized heavily by the VBDVS algorithm. Variation over time of these coefficients is very moderate and restricted to be close to zero for many time periods.

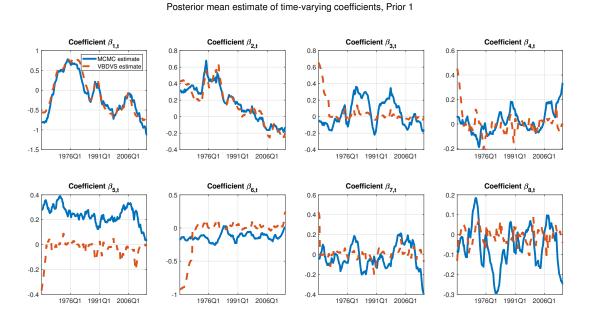


Figure 3: Posterior means of time-varying coefficient estimates from VBDVS (red dashed lines) using Prior 1. Solid lines are posterior means from a TVP model with the same predictors estimated with MCMC.

In order to examine the effect that the prior has on the time evolution of the coefficients, we change the initial condition for $w_{j,t}$ to have hyperparameters $c_{j,0} = d_{j,0}$ and we leave the same uninformative prior for $\tau_{j,t}^2$. The posterior mean coefficient estimates in Figure 4 exhibit an interesting pattern. By allowing a looser prior on w_t the parameters that are unrestricted (intercept and first lag), do exhibit larger amount of time-variation compared to the MCMC estimates. However, the remaining coefficients that were previously restricted to be close to zero, are now forced more aggressively towards zero in all time periods. This demonstrates the fact that our algorithm imposes the state-space model in equation (28), where the variance of $\beta_{j,t}$ is a function of both $w_{j,t}$ and $v_{j,t}$ (where the latter, is in turn a linear function of $\tau_{j,t}^2$). Therefore, allowing for a looser $w_{j,t}$ tends to introduce more noise in the state-space model, and for that reason the dynamic variable selection prior compensates for this increased noise by shrinking more aggressively. While there is this compensation effect and coefficient estimates won't explode as quickly as the model without the dynamic variable selection prior (recall that $\beta_{j,t}$ evolves as a non-stationary random walk), it is not

advisable to use such a lose prior on $w_{i,t}$.

Posterior mean estimate of time-varying coefficients, Prior 2

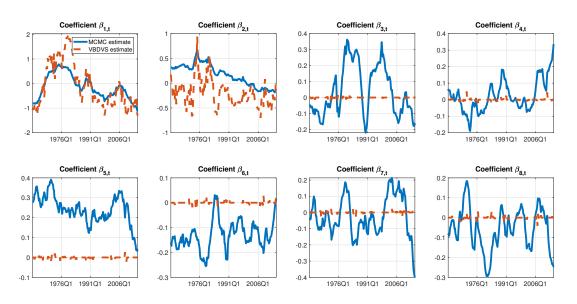


Figure 4: Posterior means of time-varying coefficient estimates from VBDVS (red dashed lines) using Prior 2. Solid lines are posterior means from a TVP model with the same predictors estimated with MCMC.

For that reason, our final prior (called Prior 3 in Table 2) returns to the conservative choice $c_{j,0} = 100$ and $d_{j,0} = 1$, and sets instead $g_0 = 1$ and $h_0 = 12$. Figure 5 shows the estimates from this prior. Once again the VBDVS estimates of the intercept and first lag coefficients are identical to the estimates from the MCMC algorithm. The remaining coefficients are again heavily penalized but there are also many time periods where these evolve unrestrictedly. As a matter of fact, this prior allows the time-varying coefficients to exhibit distinct and abrupt jumps between periods where they are zero and periods where they are unrestricted. This pattern of time-variation is more in line with the findings of the previous literature that there are pockets of predictability or, put differently, that economic predictors are short-lived (see discussion in the Introduction).

In order to have a visual assessment of the time pattern of dynamic variable selection and shrinkage, panel (a) of Figure 6 plots the posterior inclusion probabilities of each regressor associated with the time-varying coefficient estimates presented in Figure 5. These seem to show the exact periods where each coefficient moves from a state of being restricted to zero to a state where it is not zero. Panel (b) of the same figure shows the posterior mean of the stochastic volatility estimate from VBDVS versus the estimate from MCMC. These two estimates are fairly similar, showing that the specification of time-varying variances in the VBDVS does a good job at capturing known peaks in GDP deflator inflation volatility. Any

differences in volatility estimates reflect the fact that the two algorithms assume different specification of σ_t^2 and also use different priors in the estimation of $\boldsymbol{\beta}_t$.

For all these reason, we build all of our forecasting models in the next subsection based on this last prior.¹⁴

Posterior mean estimate of time-varying coefficients, Prior 3

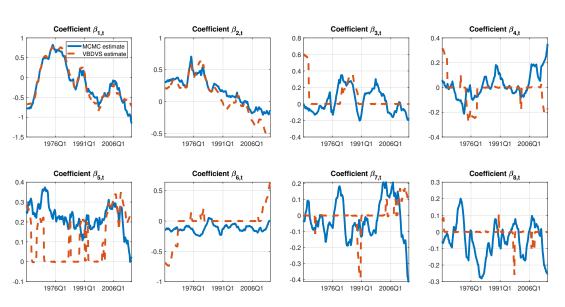


Figure 5: Posterior means of time-varying coefficient estimates from VBDVS (red dashed lines) using Prior 3. Solid lines are posterior means from a TVP model with the same predictors estimated with MCMC.

¹⁴Due to the fact that the choice $h_0 = 12$ looks in Figure 5 to penalize possibly excessively the small model with just eight coefficients, in the next subsection we adapt only this hyperparameter depending on the number of predictors we have available. Otherwise, all other hyperparameters are identical to the ones in the column labelled Prior 3 in Table 2.

Figure 6: Panel (a) shows time-varying posterior inclusion probabilities (PIPs) from VBDVS algorithm, using Prior 3. Panel (b) shows posterior means of time-varying volatility estimates from VBDVS (red dashed line) versus MCMC (solid blue line).

5.3 Forecasting inflation

We forecast inflation using models of the form

$$y_{t+h} = \alpha_t + \phi_{1,t} y_t + \phi_{2,t} y_{t-1} + x_t \beta_t + \varepsilon_{t+h}, \tag{45}$$

where y_{t+h} is h-step ahead inflation (see subsection 5.1 for a definition) regressed on an intercept, two own lags and exogenous predictors. We use a variety of forecasting models. Some benchmark models are based on equation (45) but assume constant coefficients (i.e. $\alpha_t = \alpha$, $\phi_{1,t} = \phi_1$ and so on), while others assume different sets of exogenous predictors. However, what all models have in common is that they always include an intercept and two own lags of inflation. Given that our dataset is much larger than datasets used before for forecasting inflation, in order to avoid confusion by specifying different combinations or subsets of predictors, we only distinguish four simple categories of models: i) models with no predictors (i.e. only intercept and autoregressive terms); ii) models with first five principal components as predictors; iii) models with sixty principal components as predictors; and iv) models with all 443 predictors. Our list of models representing each category is the following

- AR: benchmark AR(2) with intercept, estimated with OLS
- TVPAR: time-varying parameter version of the AR model, with stochastic volatility,

estimated with MCMC

- FAC5: Builds on benchmark AR specification by augmenting it with first five principal components estimated with OLS
- BAG/FAC5: Same predictors as FAC5, estimated as constant parameter regression using the Bagging algorithm of Breiman (1996)
- DMA/FAC5: Same predictors as FAC5, estimated as TVP regression using the Dynamic Model Averaging algorithm of Koop and Korobilis (2012)
- VBDVS/FAC5: Same predictors as FAC5, estimated as TVP regression using our Dynamic Variable Selection prior with Variational Bayes
- GPR/FAC5: Same predictors as FAC5, estimated as a Gaussian Process Regression
- SSVS/FAC60: Builds on benchmark AR specification by augmenting it with first 60 principal components, estimated using the SSVS prior with MCMC of George and McCulloch (1993)
- ELN/FAC60: Same predictors as SSVS/FAC60, estimated as a constant parameter regression using the Elastic Net algorithm of Zou and Hastie (2005)
- VBDVS/FAC60: Same predictors as SSVS/FAC60, estimated as a TVP regression using our Dynamic Variable Selection prior with Variational Bayes
- ELN/X: Builds on benchmark AR specification by augmenting it with all 443 predictors, estimated using the Elastic Net algorithm of Zou and Hastie (2005)
- PLS/X: Same predictors as in ELN/X, estimated as a constant parameter Partial Least Squares regression
- VBDVS/X: Same predictors as ELN/X, estimated as a TVP regression using our Dynamic Variable Selection prior with Variational Bayes

The choice of models is based on their simplicity and replicability. In particular, the Gaussian Process Regression, Partial Least Squares, and Elastic Net algorithms are based on built-in functions in MATLAB's Statistics and Machine Learning Toolbox (MATLAB, 2020), and are fairly easy to set up. Estimation of these models is done using default settings in MATLAB or default choices proposed by their respective creators.¹⁵ Exact details of these algorithms and their default settings is provided in the Online Supplement.

¹⁵As an example, the penalty parameter in the Elastic Net is estimated using 10-fold cross-validation.

In terms of statistical properties, all these models cover a wide spectrum of forecasting specifications. The AR(2) is a standard benchmark in economic time series forecasting, and typically performs better than a random walk (which is the benchmark for financial data). Its time-varying parameter counterpart, our second model on the list, allows for proxying for similar specifications that have been shown to forecast inflation well, see Stock and Watson (2007) and Bauwens et al. (2015). Extracting the first few principal components (factors) is possibly the most popular way of representing parsimoniously the information in a large dataset, see Stock and Watson (2016). A naive factor model uses least squares estimation on a model that has the first five principal components as exogenous predictors, while a second factor model replaces OLS with the Bagging algorithm of Breiman (1996) that allows to select the "best" factors in a static way. Next the Dynamic Model Averaging (DMA) algorithm described in Koop and Korobilis (2012) as well as our VBDVS algorithm allow to implement dynamic variable selection in a TVP setting using the same first five principal components. The Gaussian Process Regression is a very flexible nonparametric method that allows us to understand whether inflation is better described by time-varying parameters or some more complex form of nonlinearity. Moving on to models with 60 factors, we have to drop many previous specifications for computational reasons. ¹⁶ For that reason we use the SSVS algorithm of George and McCulloch (1993), which can be thought of as the static equivalent of our VBDVS algorithm. The Elastic Net of Zou and Hastie (2005) is a popular penalized likelihood estimator for high-dimensional data. Finally, our VBDVS algorithm is also estimated with a larger number of factors to find out whether its dynamic shrinkage properties are useful relative to the naive selection of the first five factors. Finally, we estimate models using all 443 exogenous predictors. The Elastic Net is again on the list, and we also include Partial Least Squares (PLS) regression. PLS is similar to principal component analysis, with the main difference being that factors are extracted with reference to the variable to be predicted. Principal components instead only explain the variability in the exogenous predictors, and it may be the case that they do not carry predictive information for the predicted variable. Finally, our VBDVS algorithm is applied to this full model with all predictors.

In terms of the prior choices used when forecasting with our VBDVS algorithm, these are based on Prior 3 described in the previous subsection, see Table 2. We only adapt how "aggressively" we shrink based on the total number of predictors in each model. For model VBDVS/FAC5 we set $h_0 = 1$, for VBDVS/FAC60 we set $h_0 = 12$ and for VBDVS/X we set $h_0 = 100$.

¹⁶For example, DMA cannot scale up to these large dimensions, Gaussian Process Regression becomes overparametrized, and Bagging becomes numerically unstable in some periods of the forecasting exercise.

Table 3: Forecasting results for GDP deflator (GDPCTPI)

		MSFE	, , , , , , , , ,	<i>-</i>	<i>y</i> (ALPL			
	h = 1	h=2	h = 4	h = 8	h = 1	h=2	h = 4	h = 8	
Models with no predictors									
AR	0.0394	0.0323	0.0308	0.0487	4.8742	4.8949	4.8374	4.6149	
TVPAR	1.04	0.96	0.99	0.83	0.30	0.29	0.46	0.31	
		Mo	ODELS WI	TH FIVE	FACTORS				
FAC5	1.00	1.08	1.53	1.57	0.02	0.04	0.02	0.01	
BAG/FAC5	0.96	1.05	1.47	1.48	0.05	0.06	0.04	0.02	
DMA/FAC5	0.84	0.79	0.94	0.95	0.26	0.27	0.22	0.18	
VBDVS/FAC5	1.30	1.20	0.97	0.83	0.15	0.14	0.28	0.20	
GPR/FAC5	1.02	0.95	1.07	1.04	0.06	0.13	0.20	0.32	
		M	ODELS W	итн 60 г	FACTORS				
SSVS/FAC60	0.99	1.03	1.44	1.42	0.01	0.05	0.09	0.13	
ELN/FAC60	1.13	1.12	1.24	1.30	0.02	0.07	0.14	0.09	
VBDVS/FAC60	1.03	0.81	0.85	0.80	0.25	0.49	0.63	0.92	
		Moi	DELS WIT	ъ 443 рг	REDICTORS				
ELN/X	0.97	1.00	1.35	1.39	0.06	0.04	0.12	0.05	
PLS/X	1.14	1.11	1.42	1.24	-0.11	0.02	-0.24	-0.42	
VBDVS/X	0.99	0.84	0.71	0.62	0.32	0.39	0.65	0.78	

Notes: All models feature an intercept and two lags of the dependent variable. Model acronyms are as follows:

 $AR: benchmark \ AR(2) \ with \ intercept \ estimated \ with \ OLS$

TVPAR: time-varying parameter version of the AR model, with stochastic volatility, estimated with MCMC

FAC5: Builds on benchmark AR specification by augmenting it with first five principal components estimated with OLS

BAG/FAC5: Same predictors as FAC5, estimated as constant parameter regression using Bagging

 $DMA/FAC5: \ Same \ predictors \ as \ FAC5, \ estimated \ as \ TVP \ regression \ using \ Dynamic \ Model \ Averaging$

VBDVS/FAC5: Same predictors as FAC5, estimated as TVP regression using our Dynamic Variable Selection prior with Variational Bayes

GPR/FAC5: Same predictors as FAC5, estimated as a Gaussian Process Regression

SSVS/FAC60: Builds on benchmark AR specification by augmenting it with first 60 principal components, estimated using an SSVS prior with MCMC

ELN/FAC60: Same predictors as SSVS/FAC60, estimated as a constant parameter regression using the Elastic Net

VBDVS/FAC60: Same predictors as SSVS/FAC60, estimated as a TVP regression using our Dynamic Variable Selection prior with Variational Bayes

ELN/X: Builds on benchmark AR specification by augmenting it with all 443 predictors, estimated using the Elastic Net

PLS/X: Same predictors as in ELN/X, estimated as a constant parameter Partial Least Squares regression

VBDVS/X: Same predictors as ELN/X, estimated as a TVP regression using our Dynamic Variable Selection prior with Variational Bayes

Entries in columns 2-5 of this Table are mean squared forecast errors (MSFEs), and columns 6-9 are average predictive likelihoods in logarithms (logAPLs). The AR model serves as a benchmark and its entries (shown in italics) are the values of MSFEs and logAPLs for each forecast horizon. Entries for each subsequent model are MSFEs and logAPLs relative to the values of the AR benchmark. MSFEs lower than one signify improvement relative to the benchmark and vice-versa for values higher than one. logAPLs that are positive signify improvement relative to the benchmark and vice-versa for negative values. Entries in boldface indicate the best performing model for each forecast statistic and for each forecast horizon.

Table 4: Forecasting results for PCE deflator (PCECTPI)

Table 4. Processing results for FCE defiator (FCECTIT)									
		\mathbf{MSFE}				ALPL			
	h = 1	h=2	h = 4	h = 8	h = 1	h=2	h = 4	h = 8	
Models with no predictors									
AR	0.1442	0.1301	0.1070	0.0980	4.6028	4.6527	4.5695	4.4313	
TVPAR	1.10	1.04	0.81	0.57	0.08	0.24	0.62	0.67	
		Mc	ODELS WI	TH FIVE	FACTORS				
FAC5	1.10	1.23	1.32	1.40	0.02	0.03	0.05	0.06	
BAG/FAC5	1.13	1.27	1.33	1.38	0.04	0.06	0.07	0.05	
DMA/FAC5	1.14	1.13	1.02	0.86	-0.07	-0.02	0.05	0.27	
VBDVS/FAC5	0.92	0.95	0.75	0.71	-0.09	-0.14	-0.21	0.29	
GPR/FAC5	1.08	1.17	1.00	0.96	0.06	0.22	0.31	0.23	
		\mathbf{N}	ODELS W	итн 60 и	FACTORS				
SSVS/FAC60	0.98	1.18	1.19	1.37	0.07	0.11	0.17	0.28	
ELN/FAC60	0.84	1.04	1.03	0.95	0.16	0.20	0.24	0.32	
VBDVS/FAC60	1.11	1.04	0.70	0.51	0.05	0.22	0.54	1.02	
		Moi	DELS WIT	н 443 рі	REDICTORS				
ELN/X	0.73	0.97	1.06	1.00	0.22	0.13	0.12	0.02	
PLS/X	0.81	0.91	0.95	0.82	0.12	0.07	0.15	-0.05	
VBDVS/X	0.93	0.84	0.62	0.51	0.11	0.27	0.57	0.69	

Notes: see notes under Table 3.

Table 5: Forecasting results for CPI (CPIAUCSL)

		\mathbf{MSFE}				ALPL		
	h = 1	h=2	h = 4	h = 8	h = 1	h=2	h = 4	h = 8
		Мо	DELS WIT	ΓΗ NO PR	EDICTORS			
AR	0.1838	0.2247	0.1621	0.1425	4.3741	4.3776	4.3663	4.2359
TVPAR	0.93	0.96	0.73	0.57	0.09	0.42	0.59	0.96
		Mc	ODELS WI	ITH FIVE	FACTORS			
FAC5	0.95	0.96	1.05	1.03	0.04	0.09	0.03	0.16
BAG/FAC5	0.95	0.97	1.01	0.92	0.06	0.10	0.09	0.16
DMA/FAC5	0.93	0.91	0.87	0.67	-0.02	0.00	0.02	0.35
VBDVS/FAC5	1.07	1.15	0.71	0.75	0.06	0.43	-0.12	0.40
GPR/FAC5	0.93	0.90	0.79	0.82	0.12	0.30	0.29	0.25
		\mathbf{N}	ODELS W	итн 60 г	FACTORS			
SSVS/FAC60	0.89	0.87	0.93	0.87	0.06	0.13	0.14	0.31
ELN/FAC60	1.08	0.81	0.89	0.72	-0.01	0.20	0.22	0.39
VBDVS/FAC60	0.98	0.88	0.67	0.54	0.10	0.45	0.56	1.01
		Moi	DELS WIT	ъ 443 рг	REDICTORS			
ELN/X	0.84	0.84	0.92	0.89	0.21	0.27	0.19	0.23
PLS/X	0.95	0.89	0.96	0.89	0.08	0.34	0.21	0.26
VBDVS/X	0.94	0.82	0.64	0.50	0.24	0.33	0.47	0.81

Notes: see notes under Table 3.

Table 6: Forecasting results for core CPI (CPILFESL)

		MSFE				ALPL	/	
	h = 1	h=2	h = 4	h = 8	h = 1	h=2	h = 4	h = 8
		Mo	DELS WIT	TH NO PR	EDICTORS			
AR	0.0221	0.0195	0.0287	0.0549	4.6432	4.6832	4.6294	4.4824
TVPAR	1.00	0.85	0.79	0.48	0.52	0.55	0.58	0.54
		$M\alpha$	DDELS WI	TH FIVE	FACTORS			
FAC5	1.89	2.37	2.17	1.41	0.02	0.04	0.09	0.15
BAG/FAC5	1.62	2.15	1.90	1.26	0.06	0.08	0.14	0.16
DMA/FAC5	1.17	1.23	0.94	0.60	0.36	0.42	0.48	0.56
VBDVS/FAC5	1.49	1.24	0.90	0.53	0.54	0.39	0.67	0.48
GPR/FAC5	1.66	1.79	1.44	0.99	0.34	0.37	0.68	0.50
		M	ODELS W	лтн 60 в	FACTORS			
SSVS/FAC60	1.73	2.18	2.00	1.05	0.03	0.04	0.13	0.19
ELN/FAC60	1.91	2.09	1.81	0.99	0.05	0.04	0.26	0.32
VBDVS/FAC60	0.91	0.79	0.72	0.47	0.72	0.78	0.93	0.92
		Moi	DELS WIT	н 443 рг	REDICTORS			
ELN/X	1.79	1.96	1.47	1.21	0.22	0.11	0.37	-0.05
PLS/X	2.53	2.87	2.05	1.27	0.13	0.00	0.14	0.19
VBDVS/X	0.99	0.78	0.60	0.43	0.71	0.78	0.99	1.07

Notes: see notes under Table 3.

We forecast h = 1, 2, 4 and 8 quarters ahead. We use 50% of the sample as our initial estimation period which, for example, for h = 1 translates to using data for the period 1960Q4-1989Q2 in order to forecast 1989Q3. We then add one new observation to the estimation sample and forecast h-step ahead, until the full sample is exhausted. Since all models that have predictors rely on the direct forecasting regression (45), for comparability we produce direct AR(2) forecasts as a special case of this equation with no predictors. We measure forecast accuracy using the mean squared forecast error (MSFE) and the average log-predictive likelihood (ALPL). The first measure is the square of the forecast error (difference between forecast and real value of y_{t+h}) averaged over the out-of-sample evaluation period, while the second measure is calculated as the logarithm of the predictive distribution evaluated at the observation y_{t+h} and also averaged over the out-of-sample evaluation period; see Bauwens et al. (2015) for more details on these two metrics.

Tables 3 to 6 present the MSFEs and ALPLs for GDP deflator, PCE deflator, CPI and Core CPI, for all competing models and all considered forecast horizons. To be precise results for the benchmark AR(2) are the values of the MSFE and ALPL statistics, while results for all other models are relative to those for the AR(2). For the MSFE this means calculating the ratio such that a number lower than one means that a certain model performs better

¹⁷The alternative would be to specify an AR(2) model linking y_t with y_{t-1} and y_{t-2} and then iterate the process h periods ahead, a procedure also known as iterative forecasting. By using direct AR(2) forecasts as the benchmark we can explicitly assess the exact contribution of various models that introduce exogenous predictors.

than the AR(2). For the ALPL relative quantities are obtained as the spread from the ALPL of the AR(2) (i.e. the logarithm of the ratio) such that positive numbers indicate that a certain model performs better than the AR(2).

The immediate message from these tables is that the VBDVS/X is the model that performs best, especially when looking at point forecast evaluation (MSFEs) for h = 2, 4, 8. In terms of density forecasts, VBDVS/X and VBDVS/FAC60 are jointly the best performing specifications. While VBDVS/FAC5 is also doing well in longer horizons, this model is always underperforming the TVPAR, that is, the TVP model that doesn't consider any predictors.

How can we explain these results? There are various stylized facts we can derive from the information in these tables. Our discussion here focuses on point forecasts (MSFE criterion), due to the fact for that metric the picture is much clearer. First, time variation seems to matter a lot, especially in the long-run. TVPAR, DMA/FAC5, and the three VBDVS specifications can improve dramatically over their constant parameter counterparts, regardless of whether these consider exogenous predictors or not. Are exogenous predictors important for forecasting? The answer depends on the variable to be forecast, the horizon considered, as well as the way each model specification utilizes the predictors. For example, for GDP deflator for h = 8 the differences in MSFE between VBDVS/X (TVP model with all available predictors) and TVPAR (TVP model with no predictors) is vast, suggesting that not only time-variation is important but also the information in exogenous predictors. However, looking at all constant parameter models with exogenous predictors, whether these predictors are observed or enter each regression via factor methods, all these methods struggle to beat the simple AR(2). This suggests the argument in the Introduction about pockets of predictability. For that reason, DMA (which is the best performing model for h=1 and h=2) and the three VBDVS specifications perform very well, with VBDVS/X providing the most dramatic improvements for h = 8 when at the same time ELN/X and PLS/X perform 24% and 39% worse than the benchmark AR(2).

For the next two inflation variables (PCE deflator and total CPI) a large number of predictors does seem to be important in the short-run, but in the long-run it looks like the largest contribution in forecasting accuracy is due to time-variation in parameters. For example, for PCE deflator and total CPI, for horizons h = 1, 2, ELN/X seems to be performing much better than the AR and the TVPAR specifications. However, for h = 4, 8 the TVPAR overtakes substantially both the AR and ELN/X specifications. While the VBDVS/X is still the best performing model for h = 4, 8, its differences to the TVPAR are statistically much smaller compared to the differences of these two models when forecasting GDP deflator. In any case, whether predictors are important or not, the VBDVS algorithm seems to be doing a very good job in shrinking irrelevant coefficients and making sure that

there is not overfitting – if there was, the VBDVS/X forecasts would be inferior to those from the TVPAR.

Finally, for core CPI all methods struggle to beat the simple AR for very short-run forecasts. The VBDVS/FAC60 and VBDVS/X models do so marginally, while many others perform as much as 150% worse than the benchmark. For longer horizons all constant parameter models continue to underperform, however, the TVP models seem to provide the most dramatic improvements, with the VBDVS/X improving almost 60% over the benchmark. Combined with the observation that the differences between the three VBDVS specifications and the TVPAR are minimal, it looks like that exogenous predictors are not relevant for core CPI. Since core CPI is based on the total CPI by removing its most volatiles components (food and energy), it might be the case that this variable is basically a random walk and even a simple time-varying intercept model (that is, a local level model as in Stock and Watson, 2007) would forecast this variable well.

It is harder to extract stylized facts for inflation forecasting based on ALPLs. This is because this metric is based on all the features of the predictive density, that is, all its moments and not just the mean. Given that predictive densities can differ a lot between specifications (e.g. they can multimodal in time-varying parameter models), it is not possible to attribute differences in ALPLs to specific modeling assumptions. However, a clear pattern that emerges is that predictors do help to improve predictive density forecasting relative to the simple AR benchmark, but the largest gains overall are achieved by time-varying parameter models. In all these comparisons the VBDVS/X is the clear winner showing that, even though this is a heavily parametrized model and could easily produce erroneous forecasts, our algorithm ensures sufficient penalization and impressive forecasting gains.

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Online Supplement to "Bayesian dynamic variable selection in high-dimensions"

Gary Koop

Dimitris Korobilis

A Settings used in competing models

While all technical details regarding our methodology are provided in detail in the paper, we have skipped details for the numerous competing algorithms used in the Monte Carlo and empirical exercises.

- DSS algorithm, Ročková and McAlinn (2017): We followed the authors and tried the various settings they suggest in their Section 7: Synthetic high-dimensional data. For our DGP the best performance was achieved with $\phi_0 = 0$, $\phi_1 = 0.98$, $\lambda_1 = 10 * (1 \phi_1.^2)$, $\lambda_0 = 0.9$ and $\Theta = 0.92$ (note that for p = 50 the authors suggest $\Theta = 0.98$, but we found that a lower value does better as p gets larger, while it doesn't deteriorate performance for p = 50).
- MCMC algorithm, Chan and Jeliazkov (2009): This is the standard time-varying parameter regression model used in economics, see for example Cogley and Sargent (2005). It consists of equations (9) and (10), where the measurement error variance follows a geometric random walk. As with VBDVS, the crucial setting that affects the amount of time-variation in regression coefficients is the prior on the state variances, which is of the form $w_j^{-1} \sim Gamma(v_1, v_2)$. We set the conservative choice $v_1 = 3$ and $v_2 = 20$, which implies that w_j has prior mean around 0.016. In order to estimate this model efficiently, we use the Gibbs sampler algorithm of Chan and Jeliazkov (2009).
- Dynamic Model Averaging, Koop and Korobilis (2012): We use standard settings described in Koop and Korobilis (2012) with $\alpha = 0.99$, $\lambda = 0.99$ and $\kappa = 0.96$.
- Bagging, Breiman (1996): With the bagging algorithm we first resample our data B times with replacement blocks of size m. For each pseudo-generated dataset we estimate with ordinary least squares using the Newey and West estimator of the covariance with lag truncation parameter $int \{T^{1/4}\}$. We select the optimal model using only those predictors that have t-statistics larger than a threshold c^* in absolute value. We forecast with the optimal model, and the bagging forecast is obtained as the average of all forecasts over the B Bootstrap replications. We set B = 1000, m = 1 and $c^* = 2.807$.
- Elastic Net, Zou and Hastie (2005): We use the MATLAB function "lasso" that is available in the Statistics and Machine Learning Toolbox. We use 10-fold cross validation for selecting the optimal λ parameter, and we fix $\alpha = 0.75$.
- Gaussian Process Regression: Gaussian Process Regression (GPR) is a very powerful machine learning method that allows flexible nonparametric estimation targeted towards prediction. We use the MATLAB function "fitrgp" that is available

in the Statistics and Machine Learning Toolbox. This is estimated using the following settings:

```
fitrgp(X,y,'Basis','linear','Optimizer','QuasiNewton','verbose',1,
'FitMethod','exact','PredictMethod','exact')
```

• Partial Least Squares: Partial Least Squares (PLS) is a method that originated in chemometrics. It allows to estimate factors that are extracted with reference to the variable to be predicted (target variable). Principal components instead maximize only the variance explained by the large dataset, and may not be optimal for prediction of the target variable. While more elegant methods have been proposed recently, such as the three-pass regression filter, the PLS is undeniably a good benchmark for assessing whether we can improve on the information content of simple principal component estimates. We use again the MATLAB function "plsregress" available in the Statistics and Machine Learning Toolbox, and we extract five factors from our dataset.

B Data Appendix

core part builds on the FRED-QD dataset compiled in McCracken and Ng (2020), and the financial (portfolio) data survey indicators from University of Michigan (https://data.sca.isr.umich.edu/); predictors of stock returns used in Welch and in Jurado et al. (2015) to extract a popular uncertainty index that are originally provided by Kenneth French (https://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data_library.html). These are augmented with additional consumer Goyal (2007) provided by Amit Goyal (http://www.hec.unil.ch/agoyal/); Commodity prices from the World Bank's Pink Sheet database (https://www.worldbank.org/en/research/commodity-markets); and key macroeconomic indicators for key economies. obtained from Federal Reserve Economic Data (FRED) of St Louis Federal Reserve Bank (https://fred.stlouisfed.org/). The following high-dimensional dataset combines several popular datasets used in macroeconomics and finance.

ogarithm; 7: first difference of percent change. The mnemonics used are those provided by the respective resources. For the Table A1 presents the 444 variables used in the empirical exercise. These are measured quarterly and cover the period 1960Q1-2018Q4. Where a variable is measured originally in higher frequency (e.g. monthly) quarterly values are obtained by to extract factors (principal components). The idea is that where some variables are aggregates of disaggregated series in the dataset, we only use the disaggregated series to extract factors. Column F denotes the code used in order to transform each variable to be approximately stationary. The transformation codes are the following 1: level (no transformation); 2: first difference; 3: second difference; 4: natural logarithm; 5: first difference of natural logarithm; 6: second difference of natural Welch and Goyal (2007) data in particular, the mnemonics are those provided in the data appendix of that paper. In the Sourcetaking the average over the quarter. Column F in Table A1 denotes whether the variable is used or not (1 or 0, respectively)column of Table A1, this paper is abbreviated as GW2008

Table A1: Quarterly large dataset

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ಬ	PCNDx	_	ಬ	Real Personal Consumption Expenditures: Nondurable Goods	FRED-QD
9	GPDIC1	0	က	Real Gross Private Domestic Investment	FRED-QD
7	FPIx	0	ಬ	Real private fixed investment	FRED-QD
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11	A014RE1Q156NBEA	Н	_	Gross private domestic investment: Change in private inventories	FRED-QD
12	GCEC1	0	ы	Real Government Consumption Expenditures & Gross Investment	FRED-QD
13	A823RL1Q225SBEA	П	_	Real Government Consumption Expenditures and Gross Investment: Federal	FRED-QD
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19	OUTNEB	0	Ю	Real Disposable Personal Income	FRED-OD
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30	IPBUSEQ	П	ro	Industrial Production: Business Equipment	FRED-QD
31	IPB51220SQ	П	ಬ	Industrial Production: Consumer energy products	FRED-QD
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1 5 1 1 6 0 6 6 8SBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0	PERMIT	_	ಬ	New Private Housing Units Authorized by Building Permits
1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 0 6 1 6 6 6 6 6 6 8 6 8 6 6 8 6 8 8 8 8 8 8 8	HOUSTMW	-	ഹ	Housing Starts in Midwest Census Region
1 5 1 1 5 1 0 5 1 1 5 1 1 5 1 1 5 1 0 6 1 0 6 1 0 6 6 1 6 6 8SBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0 8SSBEA 0 6 0	HOUSTNE	\vdash	ಬ	Housing Starts in Northeast Census Region
1 5 1 0 5 1 1 5 1 1 5 1 1 5 1 0 6 1 0 6 1 0 6 6 1 6 6 8SBEA 0 6 6 8SSBEA 0 6 9 8SSBEA 0 6 9 8SSBEA 0 6 9 8SSBEA 0 6 9	HOUSTS	_	ಬ	Housing Starts in South Census Region
0 5 1 1 5 1 1 5 1 1 5 1 0 6 1 0 6 1 1 6 6 8SBEA 0 6 1 8SSBEA 0 6 1 8SSBEA 0 6 1	HOUSTW	П	ಬ	Housing Starts in West Census Region
1 5 1 1 5 1 1 5 1 1 5 1 0 6 0 0 6 0 1 6 0 2086SBEA 0 6 0 2086SBEA 0 6 0 2086SBEA 0 6 0	$_{ m CMRMTSPLx}$	0	က	Real Manufacturing and Trade Industries Sales
1 5 1 0 6 1 0 6 1 0 6 1 1 6 0 1 6 0 2086SBEA 0 6 0 2086SBEA 0 6 1 0086SBEA 0 6 1	RSAFSx	1	က	Real Retail and Food Services Sales
1 5 1 0 6 0 0 6 1 1 6 0 2086SBEA 0 6 0 2086SBEA 0 6 0 0086SBEA 0 6 0	AMDMNOx	П	ಬ	Real Manufacturers' New Orders: Durable Goods
0 6 1 0 6 1 0 6 1 1 6 0 2086SBEA 0 6 1 2086SBEA 0 6 1 0086SBEA 0 6 1	AMDMUOx	П	ಬ	Real Manufacturers' Unfilled Orders for Durable Goods
0 6 1 0 6 0 1 6 0 2086SBEA 0 6 0 2086SBEA 0 6 1 0086SBEA 0 6 1	PCECTPI	0	9	Personal Consumption Expenditures: Chain-type Price Index
0 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	PCEPILFE	0	9	Personal Consumption Expenditures Excluding Food and Energy
1 6 086SBEA 0 6 2086SBEA 0 6 086SBEA 0 6 0086SBEA 0 6	GDPCTPI	0	9	Gross Domestic Product: Chain-type Price Index
1 6 2086SBEA 0 6 2086SBEA 0 6 2086SBEA 0 6 2086SBEA 0 6	GPDICTPI	1	9	Gross Private Domestic Investment: Chain-type Price Index
9900	IPDBS	-	9	Business Sector: Implicit Price Deflator
9 0 0	DGDSRG3Q086SBEA	0	9	Goods Personal consumption expenditures: Goods
9 0 V	DDURRG3Q086SBEA	0	9	Personal consumption expenditures: Durable goods
9 0	DSERRG3Q086SBEA	0	9	Personal consumption expenditures: Services
	DNDGRG3O086SBEA	О	9	Personal consumption expenditures: Nondurable goods

RED-QD
FRED-QD

FRED-QD

FRED-QD FRED-QD

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Table A1 (continued)

	DHCERG3Q086SBEA	0	9	ersonal consumption expenditures: Nondurable goods
	DMOTRG3Q086SBEA	-1	6]	ersonal consumption expenditures: Durable goods: Motor vehicles and parts
	DFDHRG3Q086SBEA	-	6	ersonal consumption expenditures: Durable goods: Furnishings and durable equipment
	DREQRG3Q086SBEA	-	6	ersonal consumption expenditures: Durable goods: Recreational goods and vehicles
	DODGRG3Q086SBEA	-1	6]	ersonal consumption expenditures: Durable goods: Other durable goods
	DFXARG3Q086SBEA	-1	6]	ersonal consumption expenditures: Nondurable goods: Food and beverages
	DCLORG3Q086SBEA	-	6]	ersonal consumption expenditures: Nondurable goods: Clothing and footwear
	DGOERG3Q086SBEA	-1	6	'ersonal consumption expenditures: Nondurable goods: Gasoline and other energy goods
	DONGRG3Q086SBEA	1	6 1	ersonal consumption expenditures: Nondurable goods: Other nondurable goods
	DHUTRG3Q086SBEA	-	6	ersonal consumption expenditures: Services: Housing and utilities
	DHLCRG3Q086SBEA	-	6]	
	DTRSRG3Q086SBEA	1	6]	ersonal consumption expenditures: Transportation services
	DRCARG3Q086SBEA	-1	6]	ersonal consumption expenditures: Recreation services
	DFSARG3Q086SBEA	-	6	ersonal consumption expenditures: Services: Food services and accommodations
	DIFSRG3Q086SBEA	-	6]	ersonal consumption expenditures: Financial services and insurance
	DOTSRG3Q086SBEA	-	6	Personal consumption expenditures: Other services
	CPIAUCSL	0	9	Zonsumer Price Index for All Urban Consumers: All Items
	CPILFESI	· C	9	Jonsumer Price Index for All Urban Consumers: All Items Less Food & Energy
= 1	WPSFD49207		9	Producer Price Index by Commodity for Final Demand: Finished Goods
112	PPIACO			Producer Price Index for All Commodities
1 2	WPSFD49502	· -		Producer Price Index by Commodity for Finished Consumer Goods
41	WPSFD4111	. –		Producer Price Index by Commodity for Finished Consumer Foods
115	PPIIDC		. [roducer Price Index by Commodity Industrial Commodities
116	WPSID61		9	roducer Price Index by Commodity Intermediate Materials: Supplies & Components
	WPU0561		. L	roducer Price Index by Commodity for Fuels and Related Products and Power: Crude Petroleum
	OILPRICEx	0	5	teal Crude Oil Prices: West Texas Intermediate (WTI) - Cushing, Oklahoma
	CES2000000008x	0	5	teal Average Hourly Earnings of Production and Nonsupervisory Employees: Construction
	$\rm CES3000000008x$	0	5	teal Average Hourly Earnings of Production and Nonsupervisory Employees: Manufacturing
	COMPRNFB	-	5	Annufacturing Sector: Real Compensation Per Hour
	RCPHBS	-	5	usiness Sector: Real Compensation Per Hour
123	OPHNFB	-	5	Vonfarm Business Sector: Real Output Per Hour of All Persons
124	OPHPBS	0	5	usiness Sector: Real Output Per Hour of All Persons
125	ULCBS	0	5	usiness Sector: Unit Labor Cost
126	ULCNFB		5	Nonfarm Business Sector: Unit Labor Cost
127	UNLPNBS	-	5	Nonfarm Business Sector: Unit Nonlabor Payments
128	FEDFUNDS	-	2	Edective Federal Funds Rate
129	TB3MS		2	-Month Treasury Bill: Secondary Market Rate
130	TB6MS	0	2	-Month Treasury Bill: Secondary Market Rate
131	GS1	0	2	-Year Treasury Constant Maturity Rate
132	GS10	0	2	0-Year Treasury Constant Maturity Rate
133	AAA	0	2	doody's Seasoned Aaa Corporate Bond Yield
134	BAA	0	2	doody's Seasoned Baa Corporate Bond Yield
135	BAA10YM			doody's Seasoned Baa Corporate Bond Yield Relative to Yield on 10-Year Treasury Constant Maturity
136	TB6M3Mx			-Month Treasury Bill Minus 3-Month Treasury Bill, secondary market
137	GS1TB3M×		. –	-Year Treasury Constant, Maturity Minus 3-Month Treasury Bill, secondary market
200	COLOTOSAC			Von Tronging Constant Metunity Minns 9 Month Tronging Bill Constants

140	AMBSLREAL	-		St. Louis Adjusted Monetary Base	FRED-QD
141	M1REAL			Real M1 Money Stock	FRED-QD
142	M2REAL	_		Real M2 Money Stock	FRED-QD
143	MZMREAL	\vdash		Real MZM Money Stock	FRED-QD
144	BUSLOANSx	_	ಬ	Real Commercial and Industrial Loans, All Commercial Banks	FRED-QD
145	CONSUMERX	_	ಬ	Consumer Loans at All Commercial Banks	FRED-QD
146	NONREVSLx	\vdash	ಬ	Total Real Nonrevolving Credit Owned and Securitized, Outstanding	FRED-QD
147	$REALLN_{x}$	\vdash	2	Real Real-Estate Loans, All Commercial Banks	FRED-QD
148	$TOTALSL_{x}$	\vdash	20	Total Consumer Credit Outstanding	FRED-QD
149	TABSHNOx	_	ಬ	Real Total Assets of Households and Nonprofit Organizations	FRED-QD
150	TLBSHNOx	_	ည	Real Total Liabilities of Households and Nonprofit Organizations	FRED-QD
151	LIABPIx	0	ಬ	Liabilities of Households and Nonprofit Organizations Relative to Personal Disposable Income	FRED-QD
152	TNWBSHNOx	_	2	Real Net Worth of Households and Nonprofit Organizations	FRED-QD
153	NWPIx	0	П	Net Worth of Households and Nonprofit Organizations Relative to Disposable Personal Income	FRED-QD
154	$_{ m TARESAx}$	_	വ	Real Assets of Households and Nonprofit Organizations excluding Real Estate Assets	FRED-QD
155	m HNOREMQ027Sx	П	ಬ	Real Real-Estate Assets of Households and Nonprofit Organizations	FRED-QD
156	TFAABSHNOx	_		Real Total Financial Assets of Households and Nonprofit Organizations	FRED-QD
157	TWEXMMTH			Trade Weighted U.S. Dollar Index: Major Currencies, Goods	FRED-QD
158	$ m EXSZUS_{x}$	П		Switzerland / U.S. Foreign Exchange Rate	FRED-QD
159	EXJPUSx	_	ಬ	Japan / U.S. Foreign Exchange Rate	FRED-QD
160	$EXUSUK_{x}$	_	ಬ	U.S. / U.K. Foreign Exchange Rate	FRED-QD
161	EXCAUSx	_	ည	Canada / U.S. Foreign Exchange Rate	FRED-QD
162	m UMCSENTx	0	П	University of Michigan: Consumer Sentiment	FRED-QD
163	PAGO	П	П	Current Financial Situation Compared with a Year Ago	VofMich
164	PEXP	_		Expected Change in Financial Situation in a Year	$\mathbf{UofMich}$
165	NEWS	_	П	News Heard of Recent Changes in Business Conditions	$\operatorname{UofMich}$
166	BAGO	_	П	Current Business Conditions Compared with a Year Ago	VofMich
167	BEXP	П	П	Expected Change in Business Conditions in a Year	VofMich
168	BUS12	_		Business Conditions Expected During the Next Year	VofMich
169	BUS5	_	_	Business Conditions Expected During the Next 5 Years	UofMich
170	INFEXP	_	П	Expected Change in Prices During the Next Year	$\mathbf{VofMich}$
171	DUR		П	Buying Conditions for Large Household Durables	VofMich
172	VEH	_	_	Buying Conditions for Vehicles	$\mathbf{UofMich}$
173	НОМ	_	_	Buying Conditions for Houses	VofMich
174	USASACRQISMEI	<u>.</u>	_	Passenger Car Registrations in United States	FRED-QD
175	USALOLITONOSTSAM	-	_	Leading indicators: CLI: Normalised for the United States	FRED-QD
176	BSCICP03USM665S			Composite Indicators: OECD Indicator for the United States	FRED-QD
177	${f B020RE1Q156NBEA}$	0	2	Shares of gross domestic product: Exports of goods and services	FRED-QD
178	${f B021RE1Q156NBEA}$	0	2	Shares of gross domestic product: Imports of goods and services	FRED-QD
179	IPMANSICS	0	ಬ	Industrial Production: Manufacturing (SIC)	FRED-QD
180	IPB51222S	0	20	Industrial Production: Residential Utilities	FRED-QD
181	IPFUELS	0	က	Industrial Production: Fuels	FRED-QD
182	UEMPMEAN	—	2	Duration of Unemployment	FRED-QD
183	CES0600000007		2	Average Weekly Hours of Production and Nonsupervisory Employees: Goods-Producing	FRED-QD
184	TOTRESNS	0	9 1	Total Reserves of Depository Institutions	FRED-QD
185	NONBORRES	0 (_	Reserves of Depository Institutions, Nonborrowed	FRED-QD
186	GSS	n	N	5-Year Treasury Constant Maturity Rate	FRED-QD

TB3SMFFM	1		3-Month Treasury Constant Maturity Minus Federal Funds Rate	FRED-QD
T5YFFM	Н		5-Year Treasury Constant Maturity Minus Federal Funds Rate	FRED-QD
AAAFFM	1	П	Moody's Seasoned Aaa Corporate Bond Minus Federal Funds Rate	FRED-QD
WPSID62	П	9	Producer Price Index: Crude Materials for Further Processing	FRED-QD
PPICMM	0	9	Producer Price Index: Commodities: Metals and metal products: Primary nonferrous metals	FRED-QD
CPIAPPSL	0	9		FRED-QD
CPITRNSL	Н	9	Consumer Price Index for All Urban Consumers: Transportation	FRED-QD
CPIMEDSL	П	9	Consumer Price Index for All Urban Consumers: Medical Care	FRED-QD
CUSR0000SAC	1	9	Consumer Price Index for All Urban Consumers: Commodities	FRED-QD
CUSR0000SAD	1	9	Consumer Price Index for All Urban Consumers: Durables	FRED-QD
CUSR0000SAS	Н	9	Consumer Price Index for All Urban Consumers: Services	FRED-QD
CPIULFSL	0	9	Consumer Price Index for All Urban Consumers: All Items Less Food	FRED-QD
CUSR0000SA0L2	0	9	Consumer Price Index for All Urban Consumers: All items less shelter	FRED-QD
CUSR0000SA0L5	0	9	Consumer Price Index for All Urban Consumers: All items less medical care	FRED-QD
CES0600000008	0	9	Average Hourly Earnings of Production and Nonsupervisory Employees: Goods-Producing	FRED-QD
DTCOLNVHFNM	0	9	Consumer Motor Vehicle Loans Outstanding Owned by Finance Companies	FRED-QD
DTCTHFNM	0	9	Total Consumer Loans and Leases Outstanding Owned and Securitized by Finance Companies	FRED-QD
INVEST	_	9	Securities in Bank Credit at All Commercial Banks	FRED-QD
HWIURATIOx	Н	2	Ratio of Help Wanted/No. Unemployed	FRED-QD
CLAIMSx	Н	20	Initial Claims	FRED-QD
$BUSINV_{x}$	П	ಬ	Total Business Inventories	FRED-QD
ISRATIOx	1	2	Total Business: Inventories to Sales Ratio	FRED-QD
CONSPIx	0	2	Nonrevolving consumer credit to Personal Income	FRED-QD
CP3M	0	2	3-Month AA Financial Commercial Paper Rate	FRED-QD
COMPAPFF	0	П	3-Month Commercial Paper Minus Federal Funds Rate	FRED-QD
PERMITNE	0	വ	New Private Housing Units Authorized by Building Permits in the Northeast Census Region	FRED-QD
PERMITMW	0	ಬ	New Private Housing Units Authorized by Building Permits in the Midwest Census Region	FRED-QD
PERMITS	0	വ	New Private Housing Units Authorized by Building Permits in the South Census Region	FRED-QD
PERMITW	0	ಬ	New Private Housing Units Authorized by Building Permits in the West Census Region	FRED-QD
NIKKEI225	0	ಬ	Nikkei Stock Average	FRED-QD
TLBSNNCBx	0	ಬ	Real Nonfinancial Corporate Business Sector Liabilities	FRED-QD
TLBSNNCBBDIx	0	_	Nonfinancial Corporate Business Sector Liabilities to Disposable Business Income	FRED-QD
TTAABSNNCBx	0	ಬ	Real Nonfinancial Corporate Business Sector Assets	FRED-QD
TNWMVBSNNCBx	0	ಬ	Real Nonfinancial Corporate Business Sector Net Worth	FRED-QD
TNWMVBSNNCBBDIx	0	2	Nonfinancial Corporate Business Sector Net Worth to Disposable Business Income	FRED-QD
TLBSNNBx	0	20	Real Nonfinancial Noncorporate Business Sector Liabilities	FRED-QD
TLBSNNBBDIx	0	_	Nonfinancial Noncorporate Business Sector Liabilities to Disposable Business Income	FRED-QD
TABSNNBx	0	വ	Real Nonfinancial Noncorporate Business Sector Assets	FRED-QD
TNWBSNNBx	0	ಬ	Real Nonfinancial Noncorporate Business Sector Net Worth	FRED-QD
TNWBSNNBBDIx	0	2	Nonfinancial Noncorporate Business Sector Net Worth to Disposable Business Income	FRED-QD
CNCFx	0	2	Real Disposable Business Income, Billions of 2009 Dollars	FRED-QD
S&P 500	_	ಬ	S&P's Common Stock Price Index: Composite	FRED-QD
S&P: indust	0	ಬ	S&P's Common Stock Price Index: Industrials	FRED-QD
S&P div yield	0	. 21	S&P's Composite Common Stock: Dividend Yield	FRED-QD
S&P PE ratio	0	ıς	S&P's Composite Common Stock: Price-Earnings Ratio	FRED-QD
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234	e/p		2	Earnines Price Ratio	GW2008
225	7,0	,	c	Dividend Pavour Ratio	CM/2008
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230	m/o	_	N	Book-to-Market Katlo	G W 2008
237	svar	_	Π	Stock Market Variance	GW2008
238	ntis	П	1	Net Equity Expansion	GW2008
239	lty	1	1	Long Term Yield	GW2008
240	dfy	1	П	Default Yield Spread	GW2008
241	dfr	1	П	Default Return Spread	GW2008
242	Mkt-RF	1	П	Market Excess Return (based on NYSE)	K. French
243	SMB	1	П	Small Minus Big, Sorted on Size	K. French
244	HML	1	П	High Minus Low, Sorted on Book-to-Market	K. French
245	Agric	П	П	Agric Industry Portfolio	K. French
246	Food	П	_	Food Industry Portfolio	K. French
247	Beer	П	П	Beer Industry Portfolio	K. French
248	Smoke	1	П	Smoke Industry Portfolio	
249	Tovs	1	1	Toys Industry Portfolio	K. French
250	Fun	П	П	Fun Industry Portfolio	
251	Books	-	-	Books Industry Portfolio	K. French
252	Hshld	-		Hshid Industry Portfolio	K. French
253	Clths	-	-	Clths Industry Portfolio	K. French
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261	Steel	П	_	Steel Industry Portfolio	
262	Mach	П	_	Mach Industry Portfolio	
263	ElcEq	-	П	ElcEq Industry Portfolio	
264	Autos	П	Η	Autos Industry Portfolio	
265	Aero	П	П	Aero Industry Portfolio	K. French
566	Ships	П	П	Ships Industry Portfolio	K. French
267	Mines	П	П	Mines Industry Portfolio	K. French
268	Coal	1	П	Coal Industry Portfolio	K. French
569	Oil	П	П	Oil Industry Portfolio	K. French
270	Util	1	1	Util Industry Portfolio	K. French
271	Telcm	1	П	Telcm Industry Portfolio	K. French
272	PerSv	1	П	PerSv Industry Portfolio	K. French
273	BusSv	1	П	BusSv Industry Portfolio	K. French
274	Hardw	1	_	Hardw Industry Portfolio	K. French
275	Chips	П	П	Chips Industry Portfolio	K. French
276	LabEq	1	1	LabEq Industry Portfolio	K. French
277	Paper	1	П	Paper Industry Portfolio	K. French
278	Boxes	1	П	Boxes Industry Portfolio	K. French
279	Trans	П	П	Trans Industry Portfolio	K. French
280	Whisl	П	П	Whisi Industry Portfolio	K. French

281	Rtail	1 1	Rtail Industry Portfolio	K. French
282	Meals	1 1	Meals Industry Portfolio	K. French
	Banks	-	Banks Industry Portfolio	
	Twom	· -	Income Industrial Double in	
	IIISUI DIEst		Historian Date of the Common DIEst Industry 1 October 1	
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	Fin	- , -	Fin Industry Portfolio	
	Other	T	ther Industry Portiono	
	ME1 BM2	1 1	portfolio sorted on	K. French
	ME1 BM3	1 1	(1, 3) portfolio sorted on (size, book-to-market)	K. French
290	ME1 BM4	1 1	(1, 4) portfolio sorted on (size, book-to-market)	K. French
291	ME1 BM5	1 1	(1, 5) portfolio sorted on (size, book-to-market)	K. French
292	ME1 BM6	1 1		K. French
	ME1 BM7	1 1	(size,	K. French
	ME1 BM8	1 1	(size,	K. French
	ME1 BM9	1 1	(size,	K. French
296	ME1 BM10	1 1	(1, 10) portfolio sorted on (size, book-to-market)	K. French
297	ME2 BM1	1 1	(2, 1) portfolio sorted on (size, book-to-market)	K. French
86	ME2~BM2	1 1	(2, 2) portfolio sorted on (size, book-to-market)	K. French
299	ME2 BM3	1 1	(2, 3) portfolio sorted on (size, book-to-market)	K. French
	ME2 BM4	1 1	, 4) portfolio sorted on	K. French
301	ME2 BM5	1 1		K. French
302	ME2~BM6	1 1	, 6) portfolio sorted on (size,	K. French
303	ME2 BM7	1 1		K. French
304	ME2 BM8	1 1		K. French
	ME2 BM9	1 1	, 9) portfolio sorted on	K. French
	ME2 BM10	1 1		K. French
	ME3~BM1	1 1	, 1)	
	ME3 BM2	1 1	, 2)	K. French
	ME3 BM3	1 1	(3, 3) portfolio sorted on (size, book-to-market)	K. French
_	ME3 BM4	1 1	(3, 4) portfolio sorted on (size, book-to-market)	K. French
	ME3 BM5	1 1	(3, 5) portfolio sorted on (size, book-to-market)	K. French
	ME3~BM6	1 1	(3, 6) portfolio sorted on (size, book-to-market)	K. French
	ME3 BM7	1 1	(3, 7) portfolio sorted on (size, book-to-market)	K. French
	ME3 BM8	1 1	(3, 8) portfolio sorted on (size, book-to-market)	K. French
	ME3 BM9	1 1	(3, 9) portfolio sorted on (size, book-to-market)	K. French
316	ME3 BM10	1 1	(3, 10) portfolio sorted on (size, book-to-market)	K. French
	ME4 BM1	1 1	(4, 1) portfolio sorted on (size, book-to-market)	K. French
318	ME4~BM2	1 1	(4, 2) portfolio sorted on (size, book-to-market)	K. French
	ME4 BM3	1 1	(4, 3) portfolio sorted on (size, book-to-market)	K. French
320	ME4 BM4	1 1	(4, 4) portfolio sorted on (size, book-to-market)	K. French
321	ME4~BM5	1 1	(4, 5) portfolio sorted on (size, book-to-market)	K. French
322	ME4 BM6	1 1	(4, 6) portfolio sorted on (size, book-to-market)	K. French
323	ME4 BM7	1 1	(4, 7) portfolio sorted on (size, book-to-market)	K. French
324	ME4 BM8	1 1	(4, 8) portfolio sorted on (size, book-to-market)	K. French
325	ME4 BM9	1 1	(4, 9) portfolio sorted on (size, book-to-market)	K. French
326	ME4 BM10	1 1	(4, 10) portfolio sorted on (size, book-to-market)	K. French

329 ME5 BM3 330 ME5 BM4 331 ME5 BM5		(5, 2) portfolio sorted on (size, book-to-market)	urket)	K. French
ME5 ME5	1 1	(5, 3) portfolio sorted on (size, book-to-market)	urket)	K. French
ME5	1 1	(5, 4) portfolio sorted on (size, book-to-market	urket)	K. French
	1 1	(5, 5) portfolio sorted on (size, book-to-market)	urket)	K. French
332 ME5 BM6	1 1		urket)	K. French
333 ME5 BM7	1 1	7) portfolio sorted on	urket)	K. French
334 ME5 BM8	1 1		urket)	K. French
335 ME5 BM9	1 1	(5, 9) portfolio sorted on (size, book-to-market)	urket)	K. French
336 ME5 BM10	1 1	(5, 10) portfolio sorted on (size, book-to-market)	narket)	K. French
337 ME6 BM1	1 1	(6, 1) portfolio sorted on (size, book-to-market)	\(\text{\rm rket}\)	K. French
338 ME6 BM2	1 1	(6, 2) portfolio sorted on (size, book-to-market)	urket)	K. French
339 ME6 BM3	1 1		$\operatorname{trket})$	K. French
340 ME6 BM4	1 1	(6, 4) portfolio sorted on (size, book-to-market	$\operatorname{trket})$	K. French
341 ME6 BM5	1 1	(6, 5) portfolio sorted on (size, book-to-market)	urket)	K. French
342 ME6 BM6	1 1	(6, 6) portfolio sorted on (size, book-to-market)	urket)	K. French
343 ME6 BM7	1 1	(6, 7) portfolio sorted on (size, book-to-market)	urket)	K. French
344 ME6 BM8	1 1	(6, 8) portfolio sorted on (size, book-to-market)	urket)	K. French
345 ME6 BM9	1 1		urket)	K. French
346 ME6 BM10	1 1	(6, 10) portfolio sorted on (size, book-to-market)	larket)	K. French
347 ME7 BM1	1 1	(7, 1) portfolio sorted on (size, book-to-market)	urket)	K. French
348 ME7 BM2	1 1		$\operatorname{rket})$	K. French
349 ME7 BM3	1 1	3) portfolio sorted on	$\langle { m urket} angle$	K. French
350 ME7 BM4	1 1	4) portfolio sorted on	urket)	K. French
351 ME7 BM5	1 1	5) portfolio sorted on	urket)	K. French
ME7	1 1	6) portfolio sorted on	urket)	K. French
ME7	1 1		urket)	
ME7	1 1		rket)	K. French
	1 1	(7, 9) portfolio sorted on (size, book-to-market)	urket)	K. French
ME7	0 1 1		narket)	K. French
	1 1	1) portfolio sorted on	urket)	K. French
ME8	1 1	2) portfolio sorted on	urket)	K. French
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361 ME8 BM5	1 1	5) portfolio sorted on (urket)	K. French
ME8	1 1	6) portfolio sorted on (rket)	K. French
ME8	1 1	7) portfolio sorted on	rket)	K. French
ME8	1 1		rket)	K. French
365 ME8 BM9	1 1	(8, 9) portfolio sorted on (size, book-to-market)	urket)	K. French
366 ME8 BM10	0 1 1	(8, 10) portfolio sorted on (size, book-to-market)	narket)	K. French
367 ME9 BM1	1 1		urket)	K. French
368 ME9 BM2	1 1		urket)	K. French
369 ME9 BM3	1 1	3	rket)	K. French
370 ME9 BM4	1 1	(9, 4) portfolio sorted on (size, book-to-market)	urket)	K. French
371 ME9 BM5	1 1	(9, 5) portfolio sorted on (size, book-to-market)	urket)	K. French
372 ME9 BM6	1 1		urket)	K. French
373 ME9 BM7	1 1	7) portfolio sorted on	$\operatorname{rket})$	K. French
MEG	-	8) nontfolio contod on	(102)4	K Fronch

377 MED BMA 1 (10, 1) portfolio sorted on (size, book-to-market) 378 MED BMA 1 (10, 2) portfolio sorted on (size, book-to-market) 378 MED BMA 1 (10, 3) portfolio sorted on (size, book-to-market) 380 MED BMA 1 (10, 5) portfolio sorted on (size, book-to-market) 381 MED BMA 1 (10, 5) portfolio sorted on (size, book-to-market) 382 MED BMA 1 (10, 5) portfolio sorted on (size, book-to-market) 383 Natural gas index 1 5 Commodity Prices, Corea 384 Cocos 1 5 Commodity Prices, Coffee, Robusta 385 Coffee, Robusta 1 5 Commodity Prices, Coffee, Robusta 385 Coffee, Robusta 1 5 Commodity Prices, Tea, Rolleta 385 Coffee, Robusta 1 5 Commodity Prices, Tea, Monbasa 380 Tea, Monbasa 1 5 Commodity Prices, Tea, Monbasa 381 Tea, Colombo 1 5 Commodity Prices, Tea, Monbasa 382	portfolio sorted on (size, book-to-market) odity Prices, Cocoa odity Prices, Coffee, Robusta odity Prices, Tea, Rolkata odity Prices, Tea, Mombasa odity Prices, Goconut Oil odity Prices, Gocount Oil odity Prices, Soybeans odity Prices, Soybean Oil odity Prices, Soybean Meal	K. French K. French K. French
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ME10 BM6 ME10 BM6 ME10 BM7 Natural gas index Cocoa Coffee, Arabica Coffee, Robusta Tea, Colombo Tea, Kolkata Tea, Mombasa Cocount oil Groundnut oil Palm oil Soybeans Soybean oil Soybean	1 on (size, book-to-market) 1 on (size, book-to-market) 2 dural Gas Index 3 oca 5 offee, Arabica 5 offee, Robusta 6 offee, Robusta 7 offee, Robusta 7 offee, Robusta 8 offee, Ro	IX. FIGURE
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Soybean on 1 5 Commodity Prices, Prices, Parles, Maize Barley 1 5 Commodity Prices, P	ybean Ou ybean Meal	World Balls
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Barley 1 5 Commodity Prices, Naize Sorghum 1 5 Commodity Prices, Prices, Prices, Prices, Prices, Prices, Danana Wheat 1 5 Commodity Prices, Pr		World Bank
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Sugar 1 5 Commodity Prices, Tobacco 1 5 Commodity Prices, Logs 1 5 Commodity Prices, Sawnwood 1 5 Commodity Prices, Cotton 1 5 Commodity Prices, Rubber 1 5 Commodity Prices, Lead 1 5 Commodity Prices, Tin 1 5 Commodity Prices, Zinc 1 5 Commodity Prices, Zinc 1 5 Commodity Prices,	Shrimps, Mexican	World Bank
Tobacco 1 5 Commodity Prices, Commodity Prices, Sawnwood Logs 1 5 Commodity Prices, Commodity Prices, Cotton Rubber 1 5 Commodity Prices, Commodity Prices, Lead Copper 1 5 Commodity Prices, Tries, Tr	Sugar, World	World Bank
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Sawnwood 1 5 Commodity Prices, Cotton Rubber 1 5 Commodity Prices, Copper Copper 1 5 Commodity Prices, Lead Lead 1 5 Commodity Prices, Tin Tin 1 5 Commodity Prices, Commodity Prices, Tin Nickel 1 5 Commodity Prices, Commodi	Logs, Malaysian	World Bank
Cotton 1 5 Commodity Prices, Rubber 1 5 Commodity Prices, Copper 1 5 Commodity Prices, Lead 1 5 Commodity Prices, Tin 1 5 Commodity Prices, Nickel 1 5 Commodity Prices, Zinc 1 5 Commodity Prices,	Sawnwood, Malaysian	World Bank
Rubber 1 5 Commodity Prices, Copper 1 5 Commodity Prices, Lead 1 5 Commodity Prices, Tin 1 5 Commodity Prices, Nickel 1 5 Commodity Prices, Zinc 1 5 Commodity Prices,	Cotton, A Index	World Bank
Copper 1 5 Commodity Prices, Lead 1 5 Commodity Prices, Tin 1 5 Commodity Prices, Nickel 1 5 Commodity Prices, Zinc 1 5 Commodity Prices,	Rubber, SGP/MYS	World Bank
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	nc	World Bank
418 Gold 1 5 Commodity Prices, Gold	plc	World Bank
419 Platinum 1 5 Commodity Prices, Platinum	atinum	World Bank
1 5 0	lver	World Bank
421 JPNPROINDQISMEI 1 5 Production of Total Industry in Japan	ndustry in Japan	FRED

Table	Table A1 (continued)				
422	LRHUTTTTJPQ156S	-	ಬ	Harmonized Unemployment Rate: Total: All Persons for Japan	FRED
423	JPNCPIALLQINMEI	П	ស	Consumer Price Index of All Items in Japan	FRED
424	JPNLOLITONOSTSAM	П	Н	Leading indicators: CLI: Normalised for Japan	FRED
425	DEUPROINDQISMEI	П	വ	Production of Total Industry in Germany	FRED
426	OPCNRE01DEQ661N	П	ಬ	Total Cost of Residential Construction for Germany	FRED
427	IRLTLT01DEQ156N	П	2	Long-Term (10-year) Government Bond Yields for Germany	FRED
428	DEUCPIALLQINMEI	П	ಬ	Consumer Price Index of All Items in Germany	FRED
429	SPASTT01DEQ661N	П	ಬ	Total Share Prices for All Shares for Germany	FRED
430	QDEPAMUSDA	П	ಬ	Total Credit to Private Non-Financial Sector for Germany	FRED
431	GBRPROINDQISMEI	П	ស	Production of Total Industry in the United Kingdom	FRED
432	IRLTLT01GBQ156N	П	2	Long-Term (10-year) Government Bond Yields for the United Kingdom	FRED
433	GBRCPIALLQINMEI	П	വ	Consumer Price Index of All Items in the United Kingdom	FRED
434	LMUNRRTTGBQ156S	Н	2	Registered Unemployment Rate for the United Kingdom	FRED
435	SPASTT01GBQ661N	Н	ಬ	Total Share Prices for All Shares for the United Kingdom	FRED
436	GBRGFCFQDSMEI	П	ស	Gross Fixed Capital Formation in United Kingdom	FRED
437	GBRLOLITONOSTSAM	П	П	Leading indicators: CLI: Normalised for the United Kingdom	FRED
438	CANPROINDQISMEI	П	ಬ	Production of Total Industry in Canada	FRED
439	WSCNDW01CAQ489S	П	4	Total Dwellings and Residential Buildings by Stage of Construction, Started for Canada	FRED
440	IRLTLT01CAQ156N	П	2	Long-Term (10-year) Government Bond Yields for Canada	FRED
441	LRUNTTTTCAQ156S	П	2	Unemployment Rate: Aged 15 and Over: All Persons for Canada	FRED
442	QCAPAM770A	Н	ಬ	Total Credit to Private Non-Financial Sector for Canada	FRED
443	SPASTT01CAQ661N	Н	ಬ	Total Share Prices for All Shares for Canada	FRED
444	CANLOLITONOSTSAM	П	Н	Leading indicators: CLI: Normalised for Canada	FRED